

# Statistical physics and statistical inference

**Marc Mézard**

Ecole normale supérieure  
PSL University

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Conférence René Pellat



# What is inference?

## Statistics

Infer a hidden rule, or hidden variables, from data.

Restricted sense : find parameters of a probability distribution

*Urn with 10.000 balls. Draw 100, find 70 white balls and 30 black*

*Best guess for the composition of the urn? How reliable? Probability that it has 6000 white- 4000 black?*

If only black and white balls , with fraction  $x$  of white, probability to pick-up 70 white balls is  $\binom{100}{70} x^{70} (1 - x)^{30}$

Log likelihood of  $x$  :  $L(x) = 70 \log x + 30 \log(1 - x)$

Maximum at  $x^* = .7$  Probability of .6 :  $e^{L(.6) - L(.7)}$



# Bayesian inference

Unknown parameters	$x$		Prior	$P(x)$
Measurements	$y$		Likelihood	$P(y x)$

Posterior

$$P(x|y) = \frac{P(y|x)P(x)}{P(y)}$$



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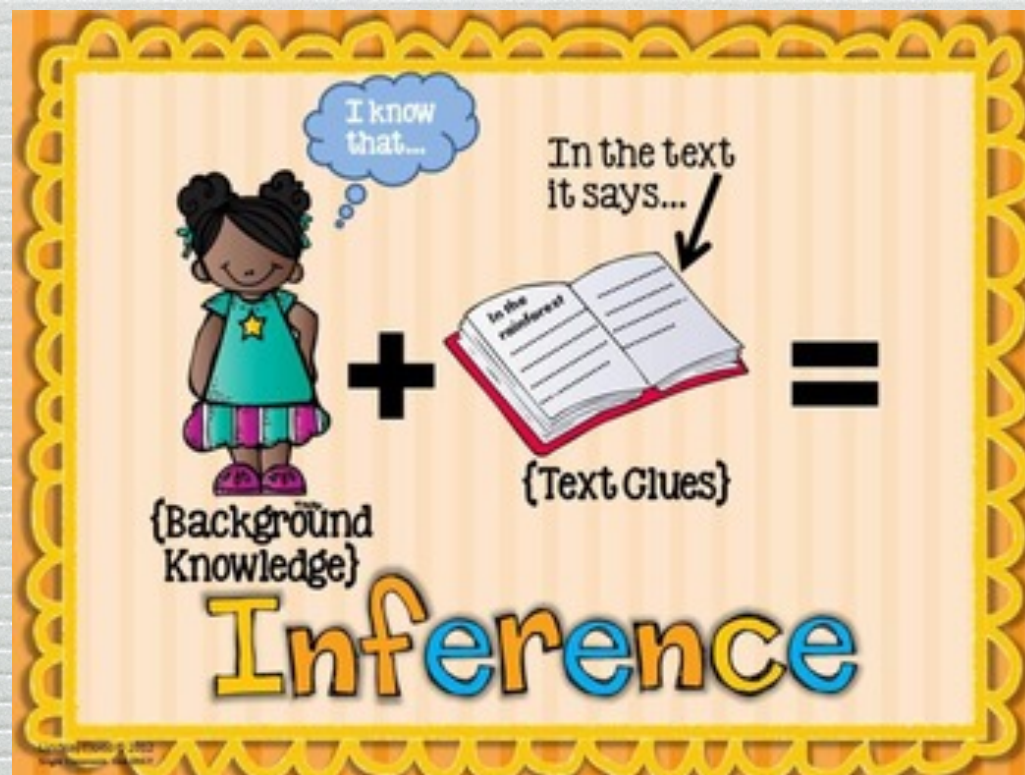


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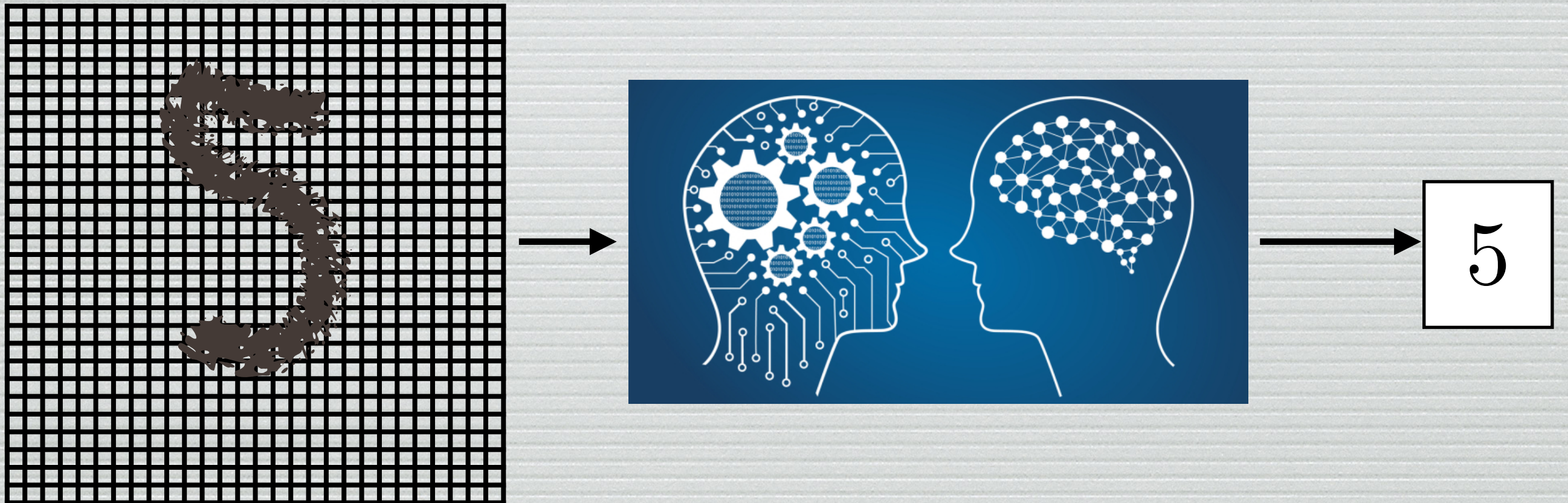
$$P(\boxed{x}|y) = \frac{P(y|\boxed{x})P(\boxed{x})}{P(y)}$$





# What is inference?

Artificial intelligence,  
machine learning



Find a machine that reads handwritten digits...

...inferring its parameters from examples



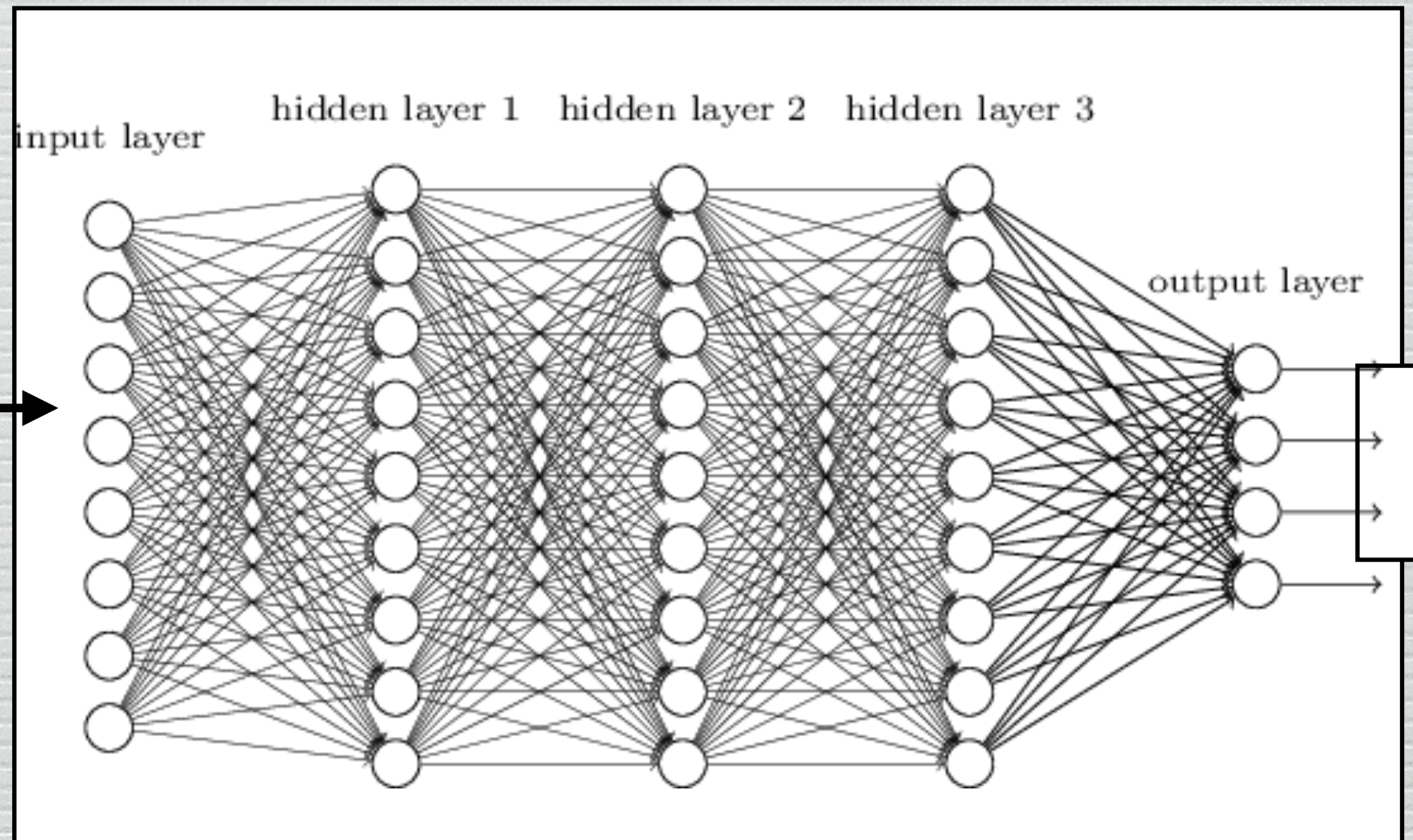
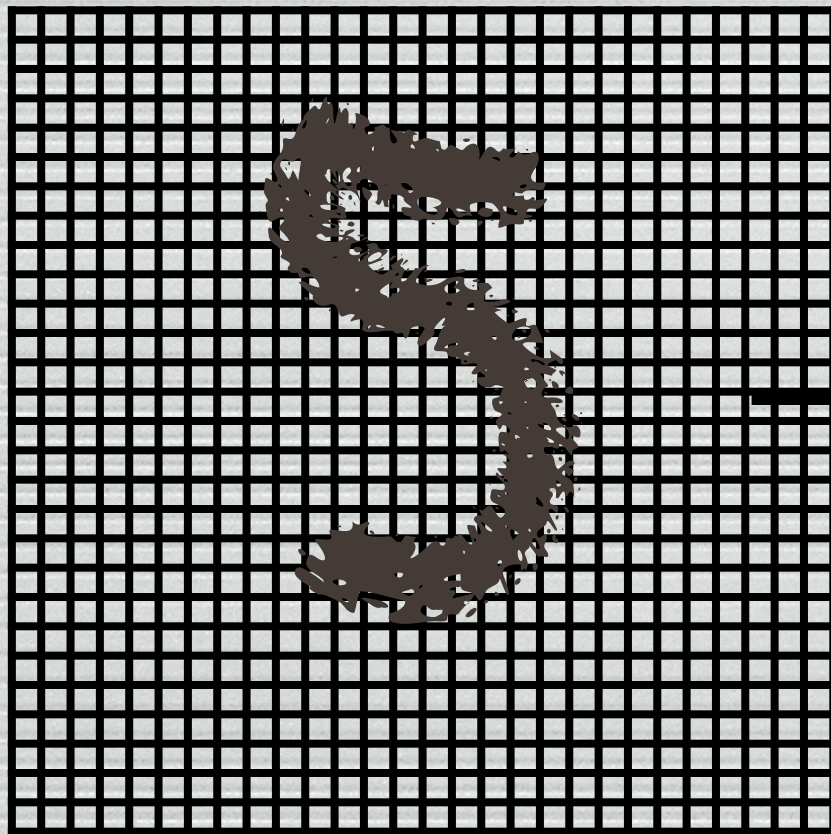


MNIST database : 70,000 images of digits, segmented,  
28  $\times$  28 pixels each, greyscale. Known output  
(supervised learning)



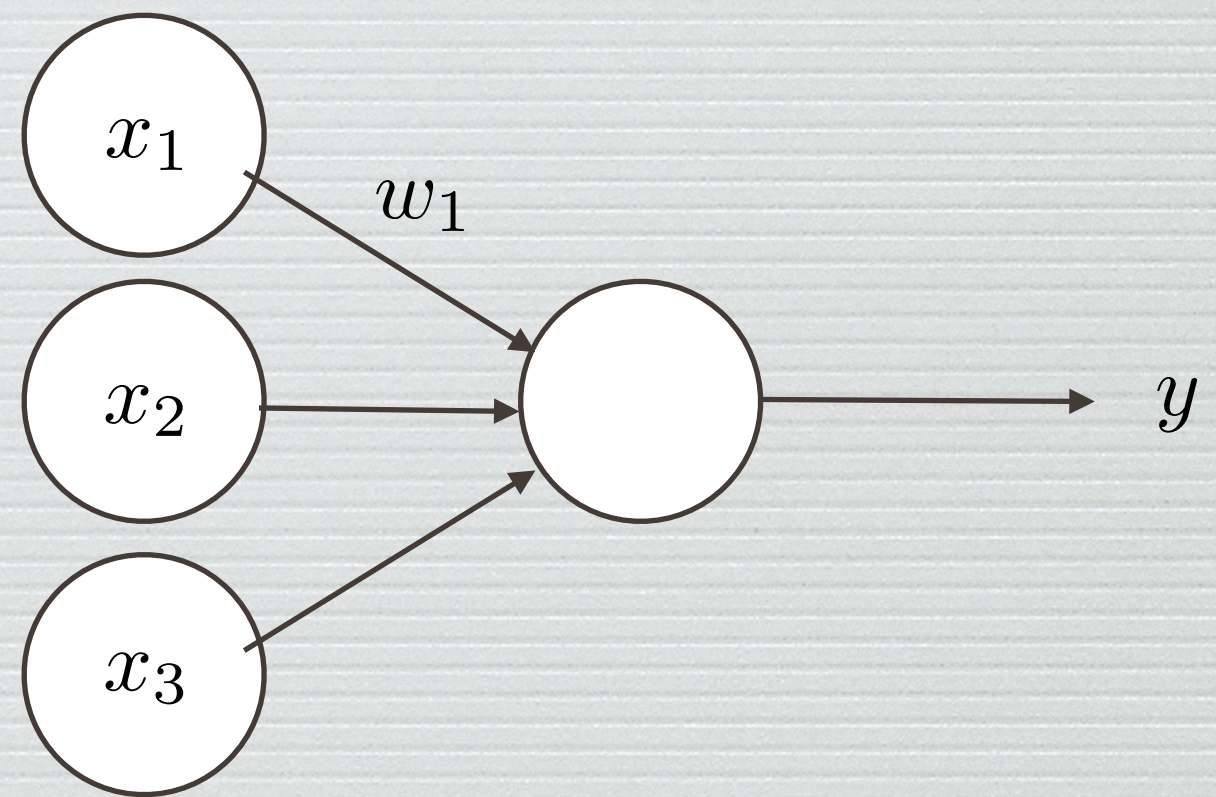
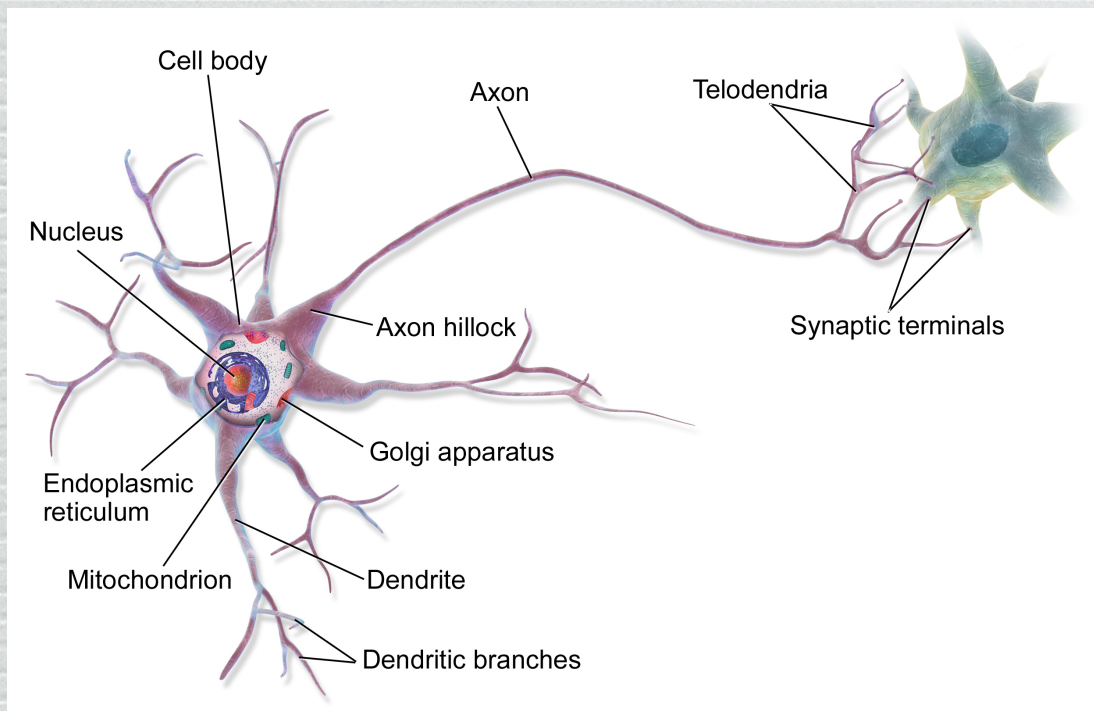
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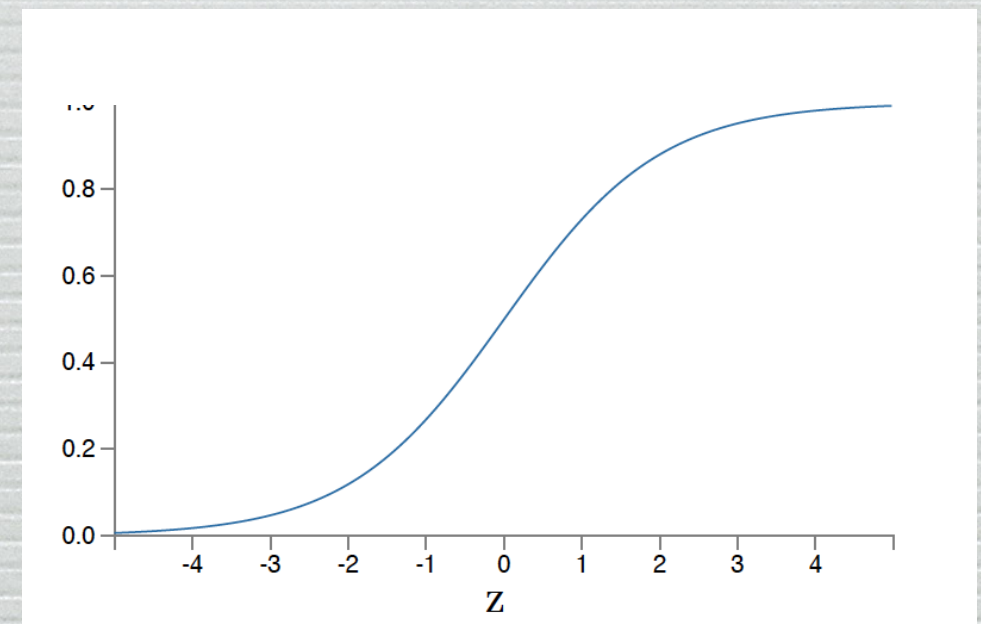
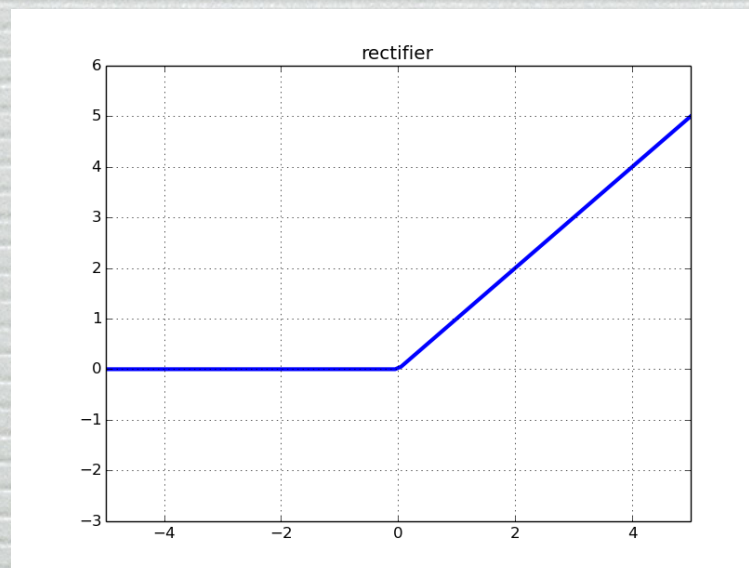
« Neural network » : artificial neurons





$$y = f(w_0 + w_1x_1 + w_2x_2 + w_3x_3)$$

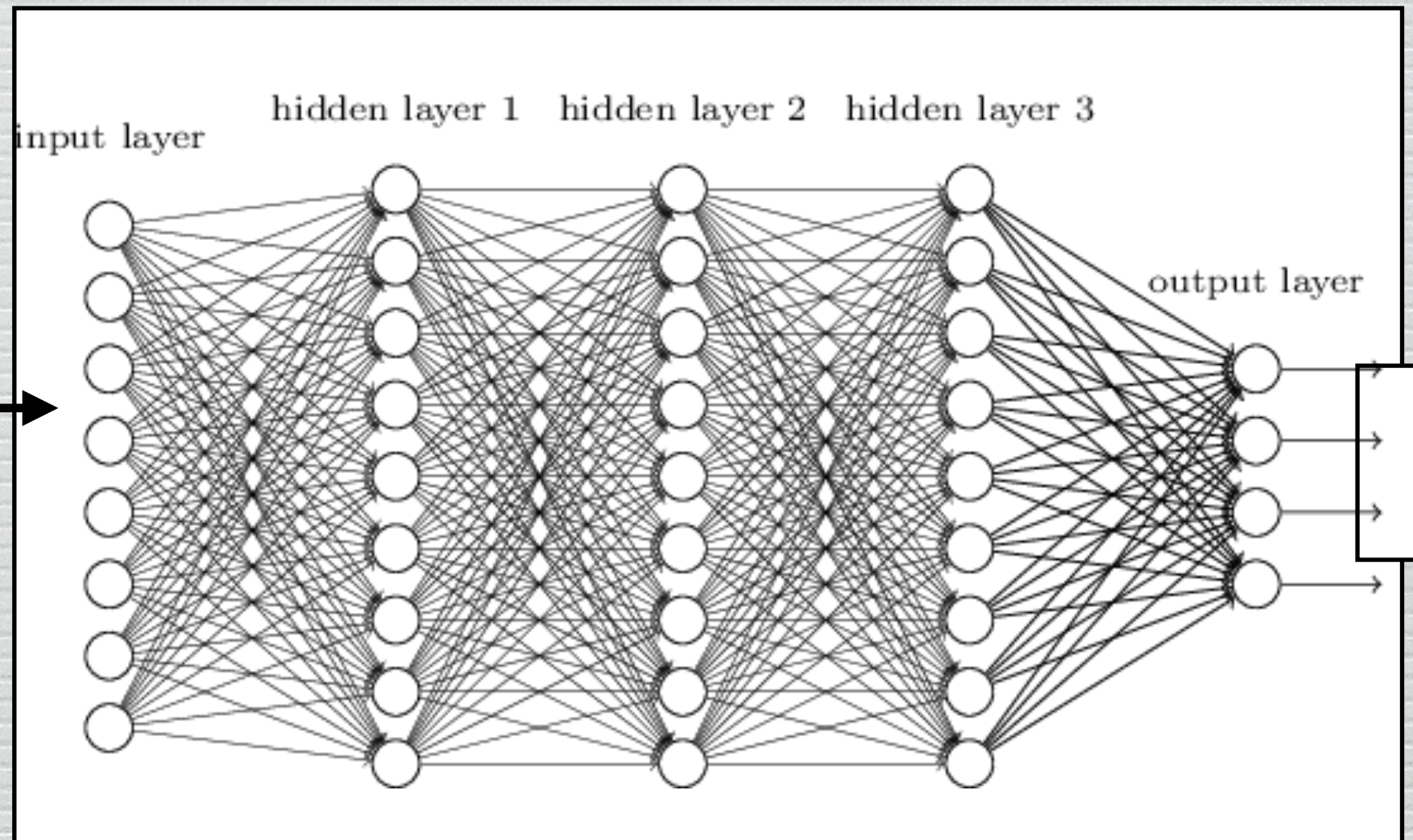
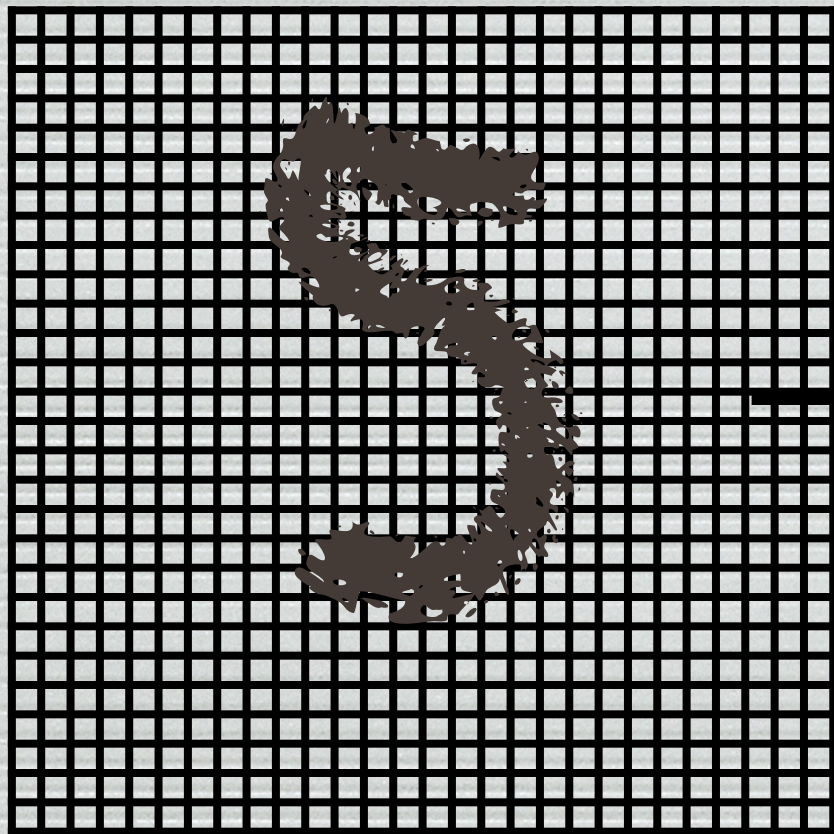
## Formal neural network





# What is inference?

Artificial intelligence,  
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Machine with hundreds of thousands of parameters,  
trained on very large data base: infer the parameters from  
data (supervised learning)



# Statistical inference

Challenge = rules with **many hidden parameters**. eg :  
machine learning with large machine and big data, decoding  
in communication,...

$$x = (x_1, \dots, x_N) \quad N \gg 1$$

Many measurements  $y = (y_1, \dots, y_M) \quad M \gg 1$

Measure of the amount of data  $\alpha = M/N$

➡ **Algorithms**

➡ **Prediction on the quality of inference**, on the  
performance of the algorithms, on the type of situations  
where they can be applied



# Bayesian inference with many unknown and many measurements

Unknown parameters  $x = (x_1, \dots, x_N)$  Prior  $P^0(x)$   
Measurements  $y = (y_1, \dots, y_M)$   $P(y|x)$

**Bayesian inference**  $P(x|y) \propto P(y|x)P^0(x)$

**Often** (but not necessarily):

Independent measurements  $P(y|x) = \prod_{\mu} P_{\mu}(y_{\mu}|x)$

Factorized prior  $P^0(x) = \prod_i P_i^0(x_i)$

Posterior  $P(x) = \frac{1}{Z(y)} \left( \prod_i P_i^0(x_i) \right) \exp \left[ - \sum_{\mu} E_{\mu}(x, y_{\mu}) \right]$

$$E_{\mu}(x, y_{\mu}) = -\log P_{\mu}(y_{\mu}|x)$$



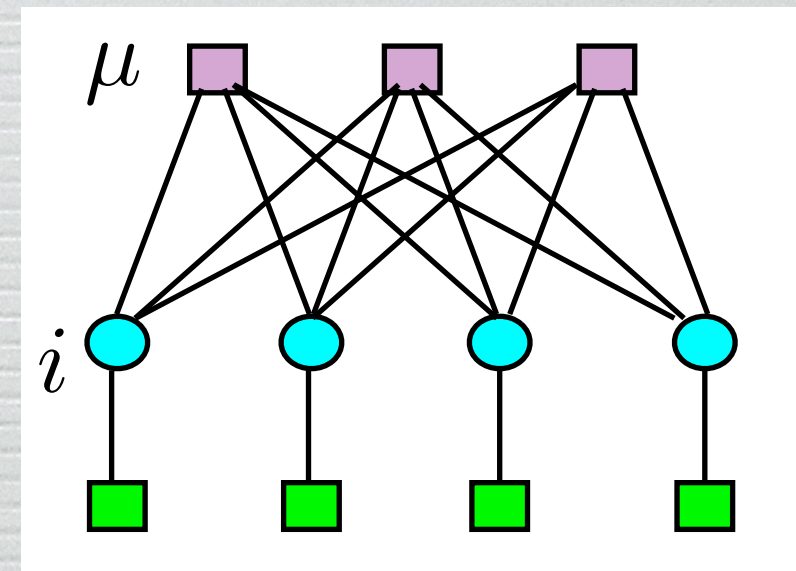
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## Statistical mechanics.

- ◆ Discrete or continuous variables  $x_i$
- ◆ Interactions through  $e^{-E_{\mu}(x, y_{\mu})}$  can be
  - pairwise :  $E_{\mu} = J_{\mu} x_{i(\mu)} x_{j(\mu)}$
  - multibody
- ◆ Disordered system, ensemble
- ◆ Thermodynamic limit, phase transitions



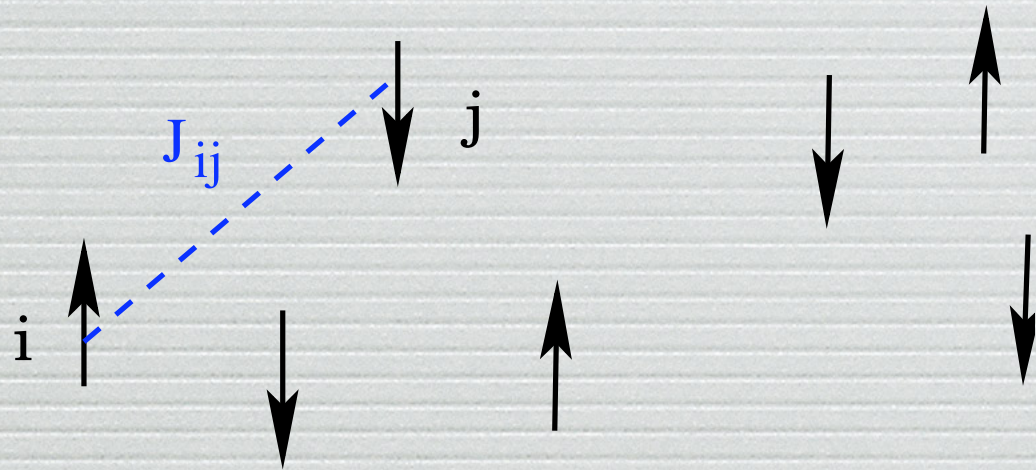
« Spin glass »



# Spin glasses

- Disordered magnetic systems

e.g.: CuMn



$$s_i = \pm 1$$

$$E = - \sum_{i,j} J_{ij} s_i s_j$$

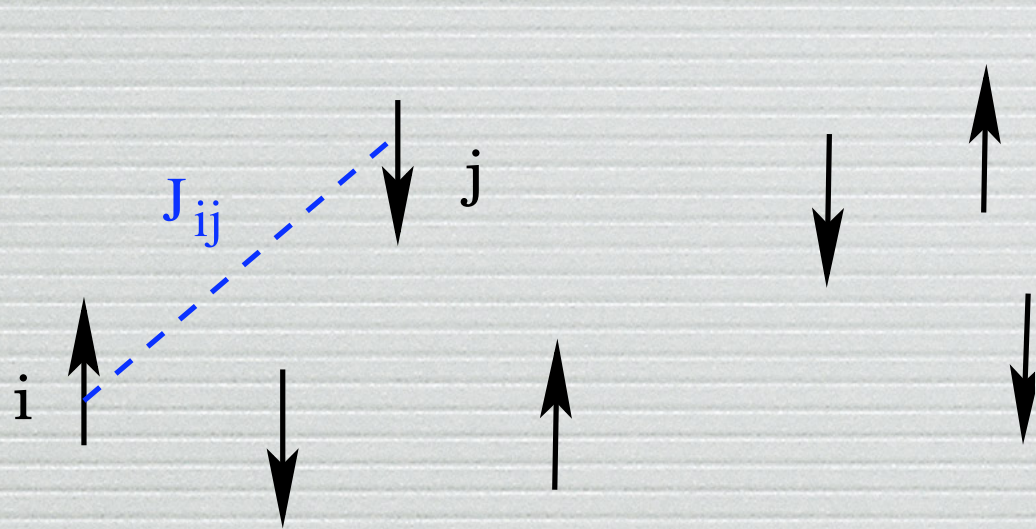
$$P(s_1, \dots, s_N) = \frac{1}{Z} e^{-E/T}$$



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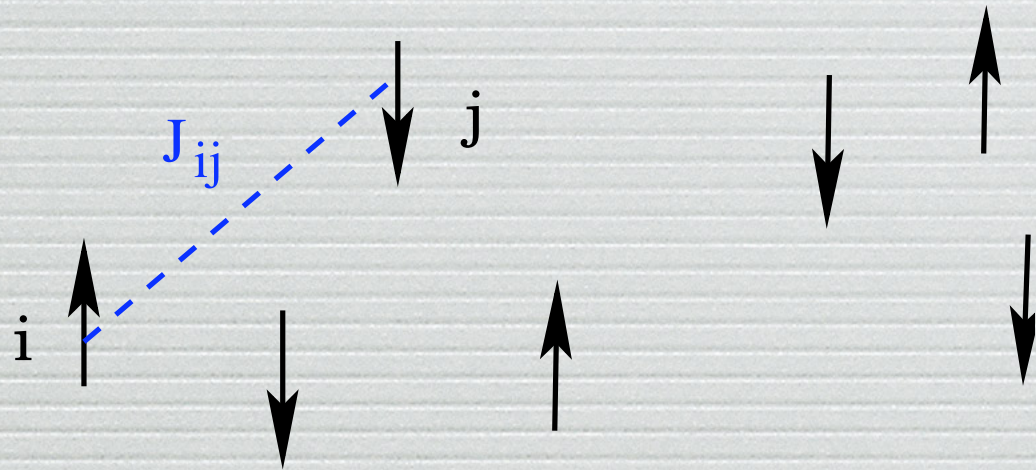
➡ Each spin 'sees' a different local field



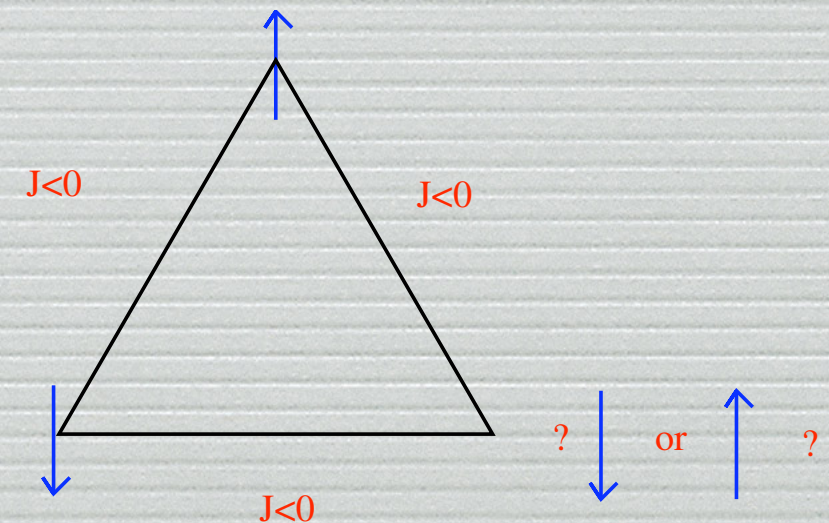
# Phase transition with many states: spin glasses

- Many atoms, microscopic interactions are known, “disordered systems”

e.g.: CuMn



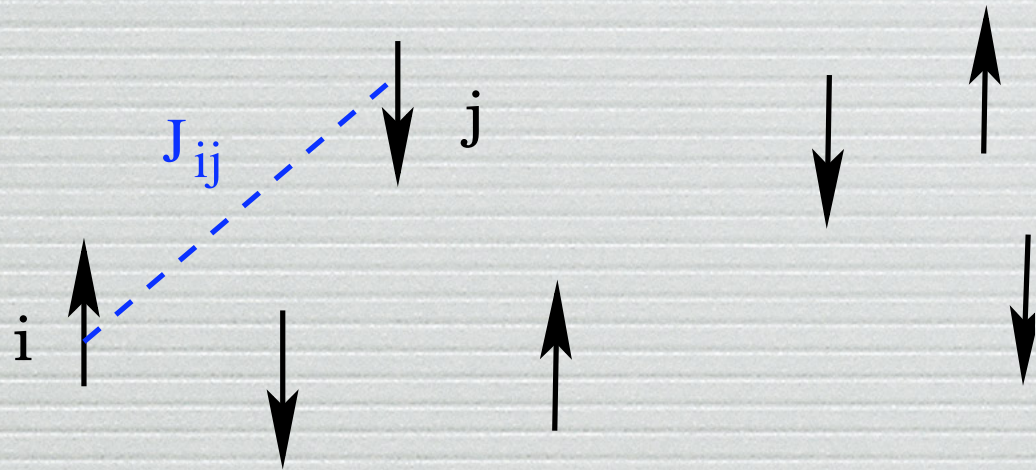
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- ➡ Low temperature: frustration



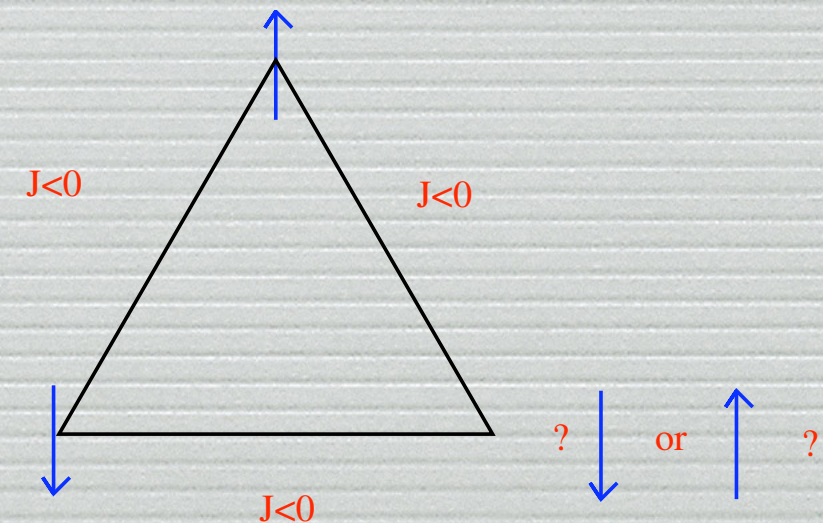


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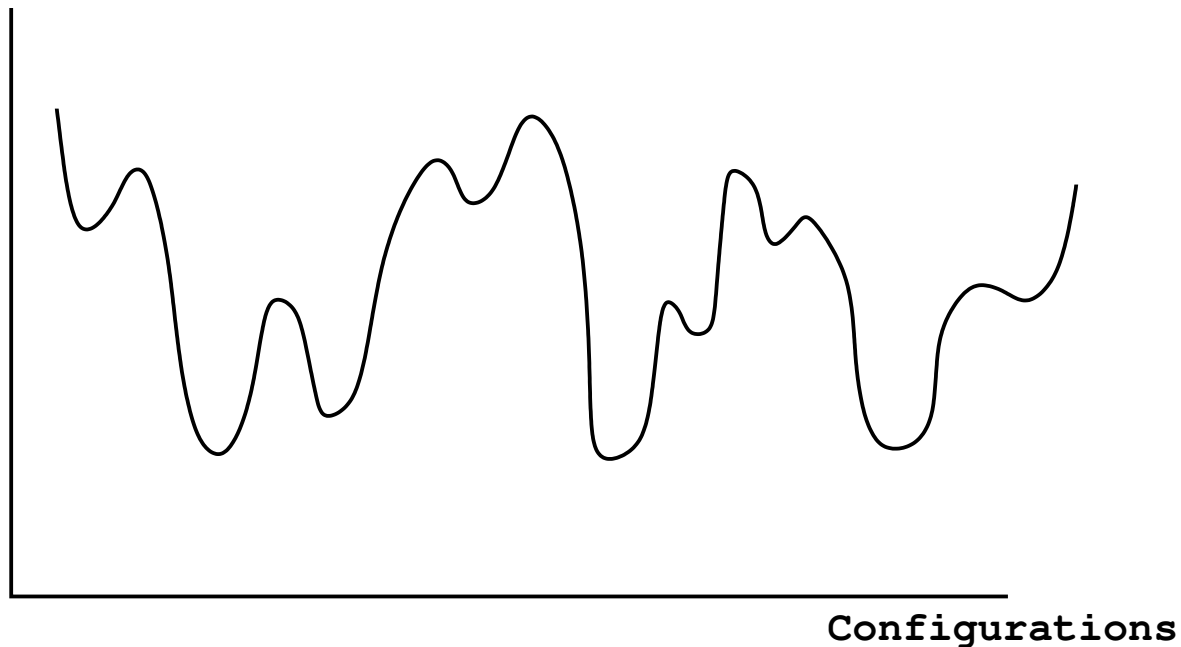
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- ➡ Difficult to find min. of  $E$





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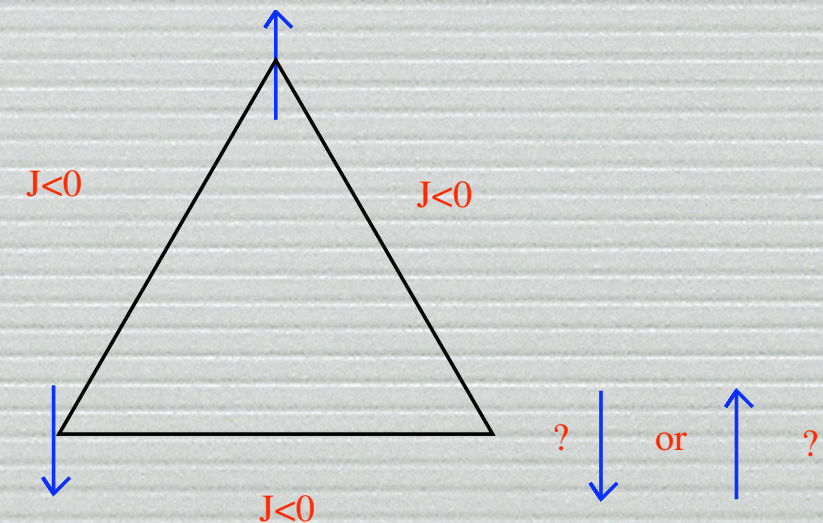


Many quasi-ground states unrelated by symmetries, many metastable states

Slow dynamics, aging

Spin glass

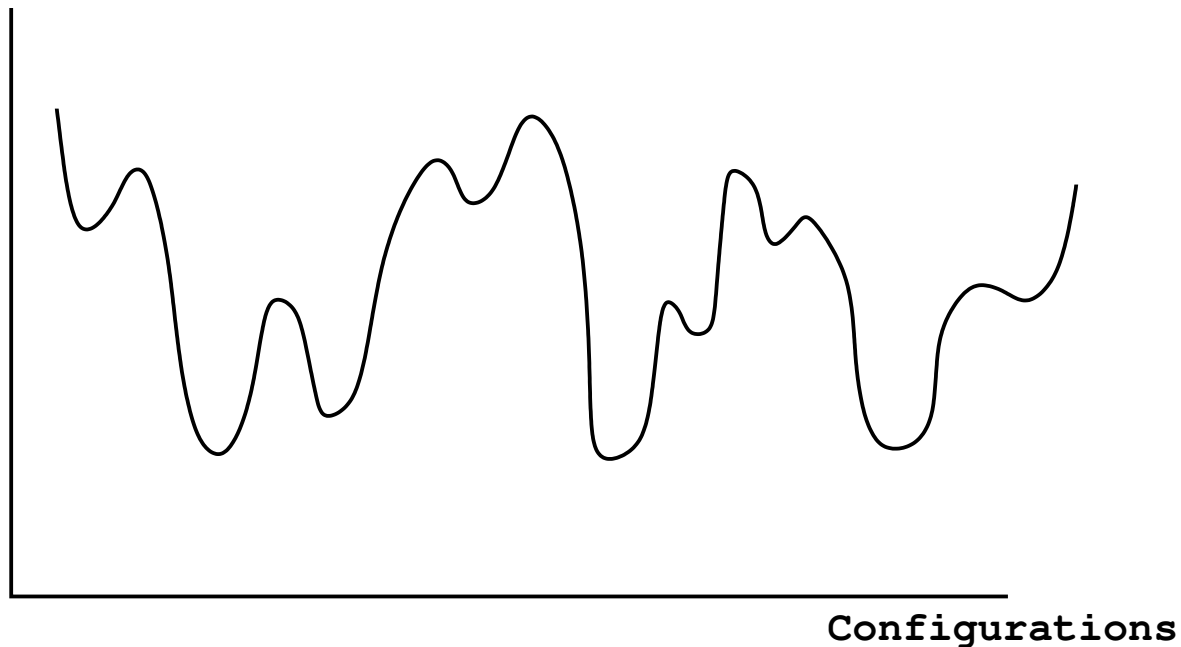
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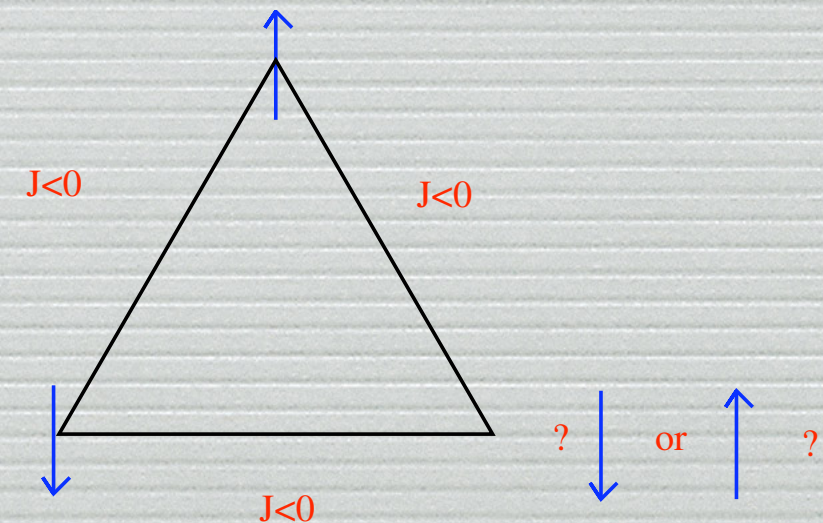
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*Useless, but thousands of papers...*



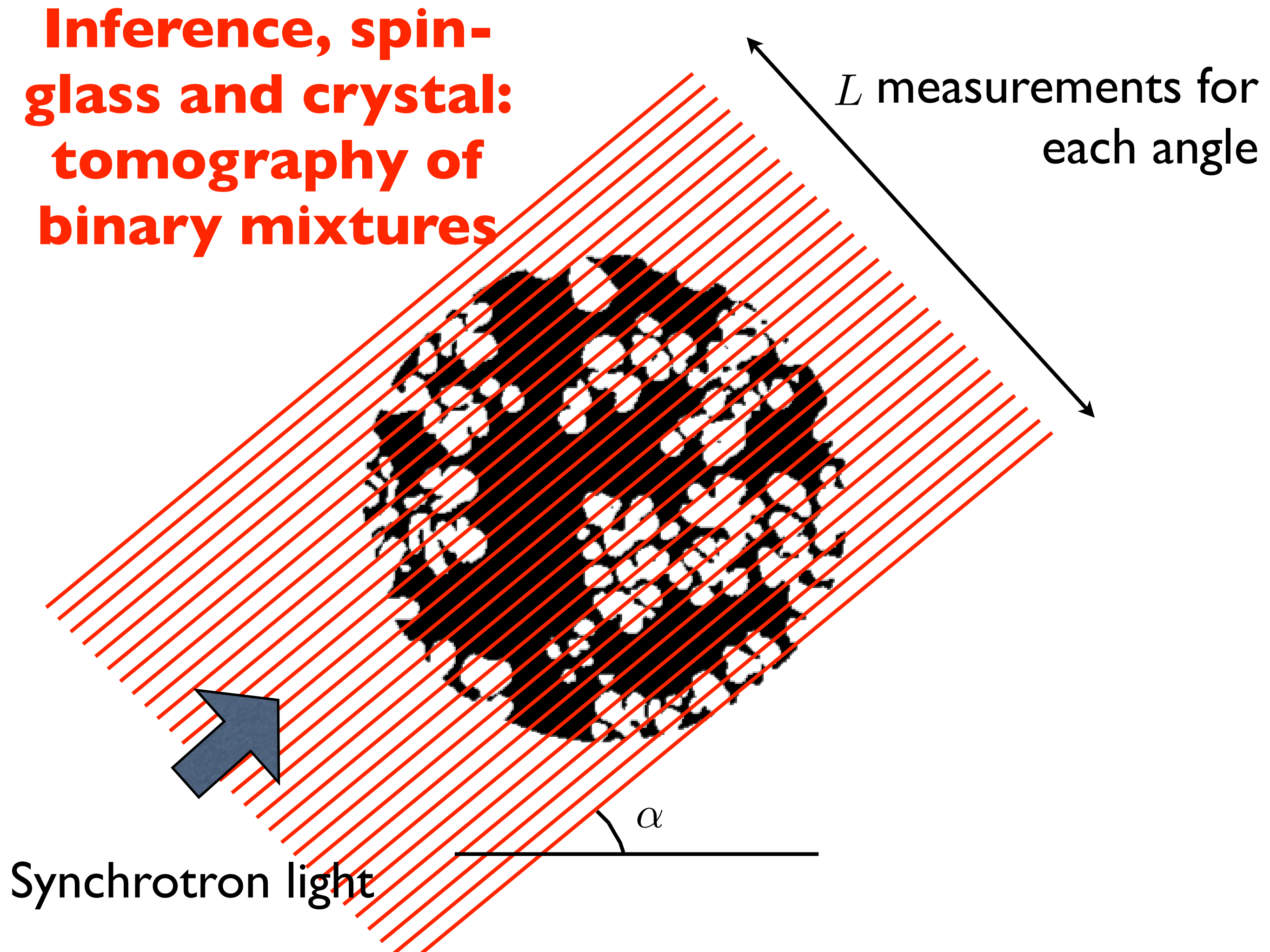


# **Inference, spin- glass and crystal: tomography of binary mixtures**



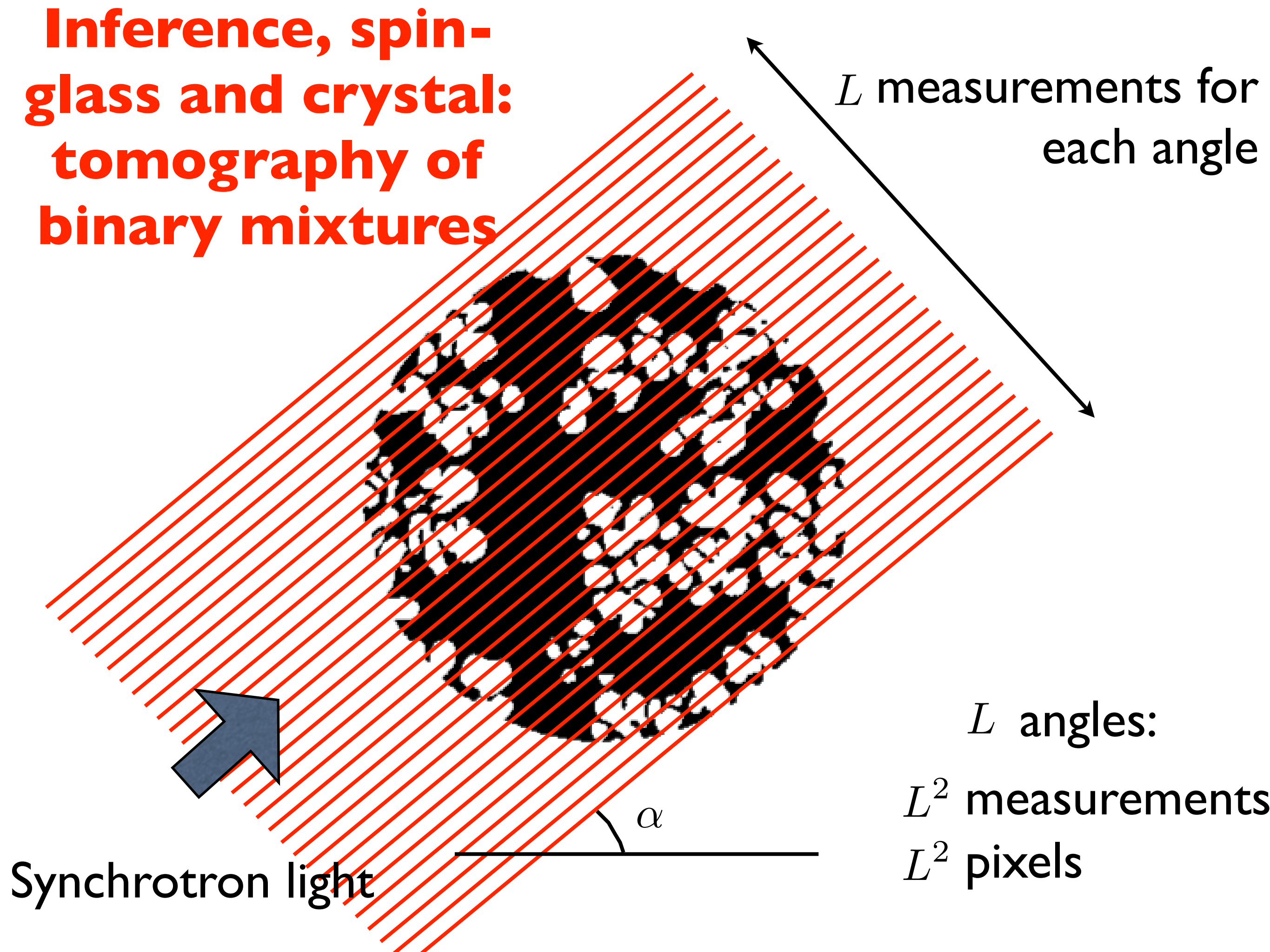


# Inference, spin-glass and crystal: tomography of binary mixtures



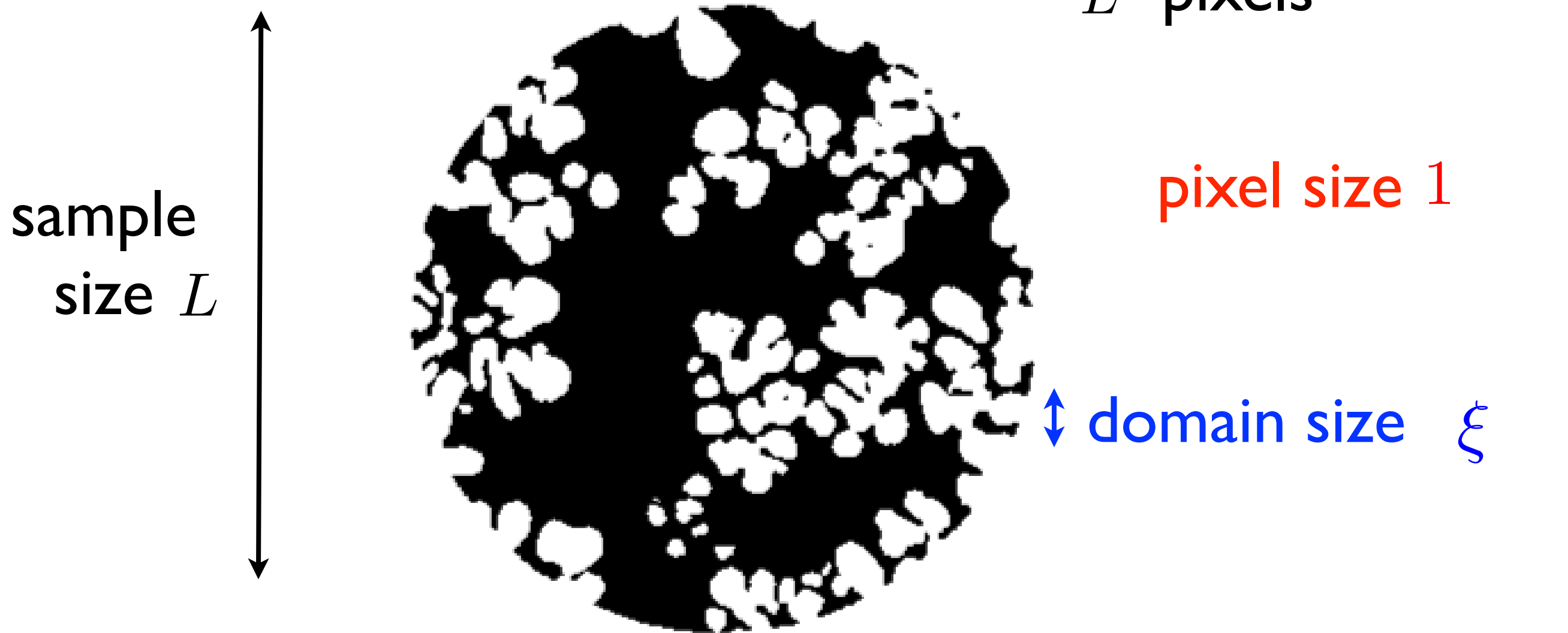


# Inference, spin-glass and crystal: tomography of binary mixtures





# Tomography of binary mixtures

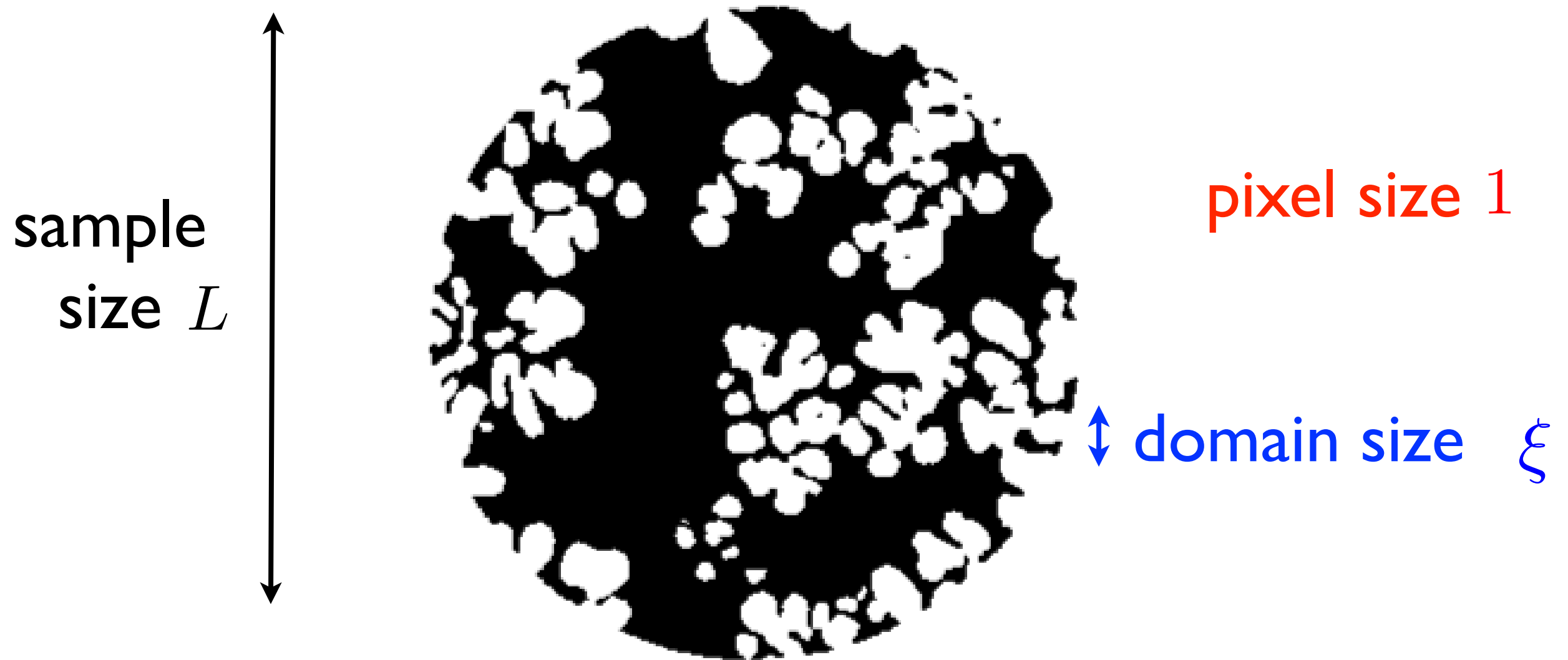


If the size of domains is  $\gg$  pixel: possible to  
reconstruct with  $\ll L^2$  measurements

$$\xi \gg 1$$



# Tomography of binary mixtures



If the size of domains is  $\gg$  pixel: possible to  
reconstruct with  $\ll L^2$  measurements

$$\xi \gg 1$$



# Tomography of binary mixtures

This picture, digitalized on  
 $1000 \times 1000$  grid, can be  
reconstructed from  
measurements with  
16 angles

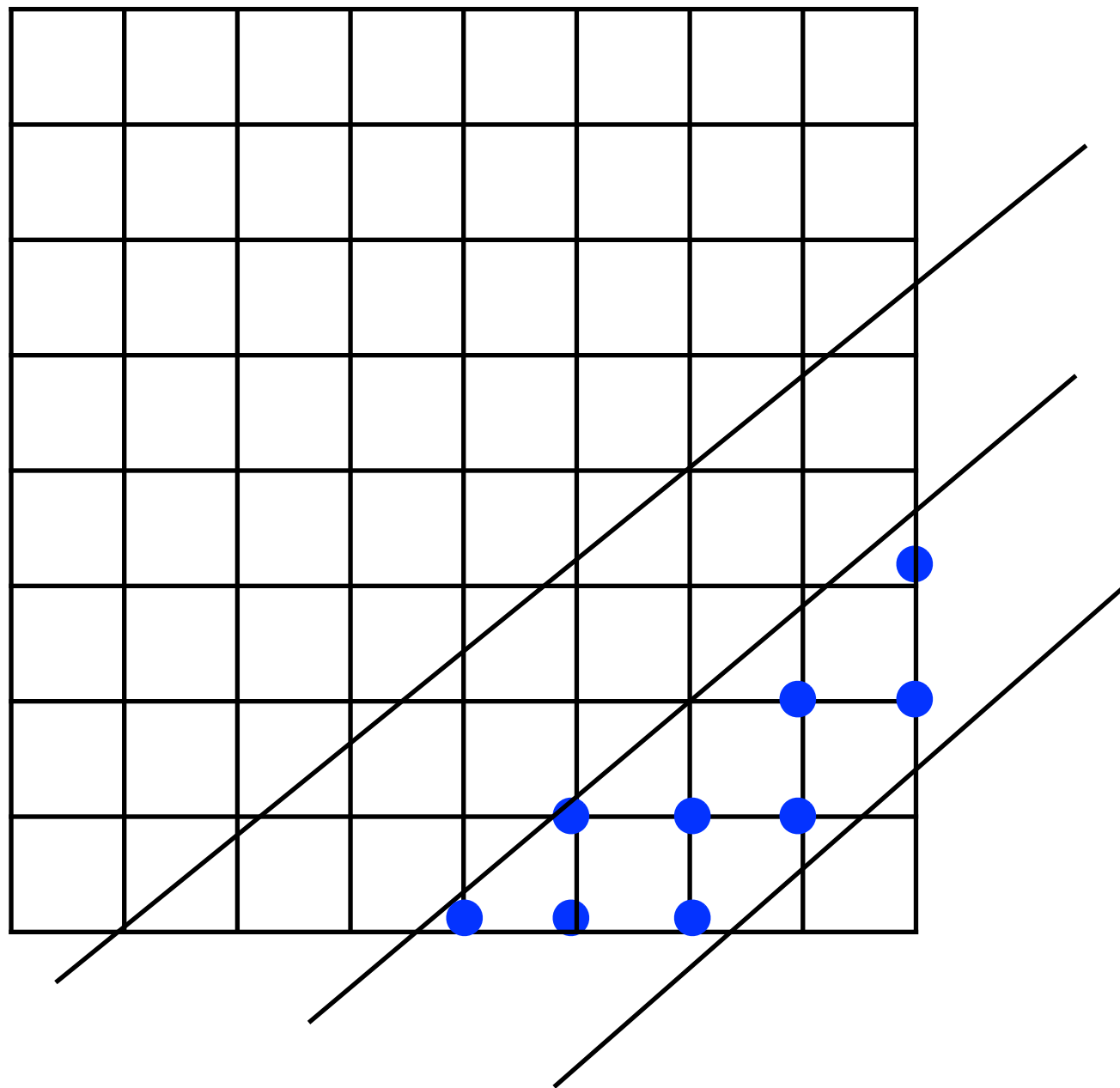


## Compressed sensing

Gouillart et al.,  
Inverse problems 2013

If the size of domains is  $\gg$  pixel: possible to  
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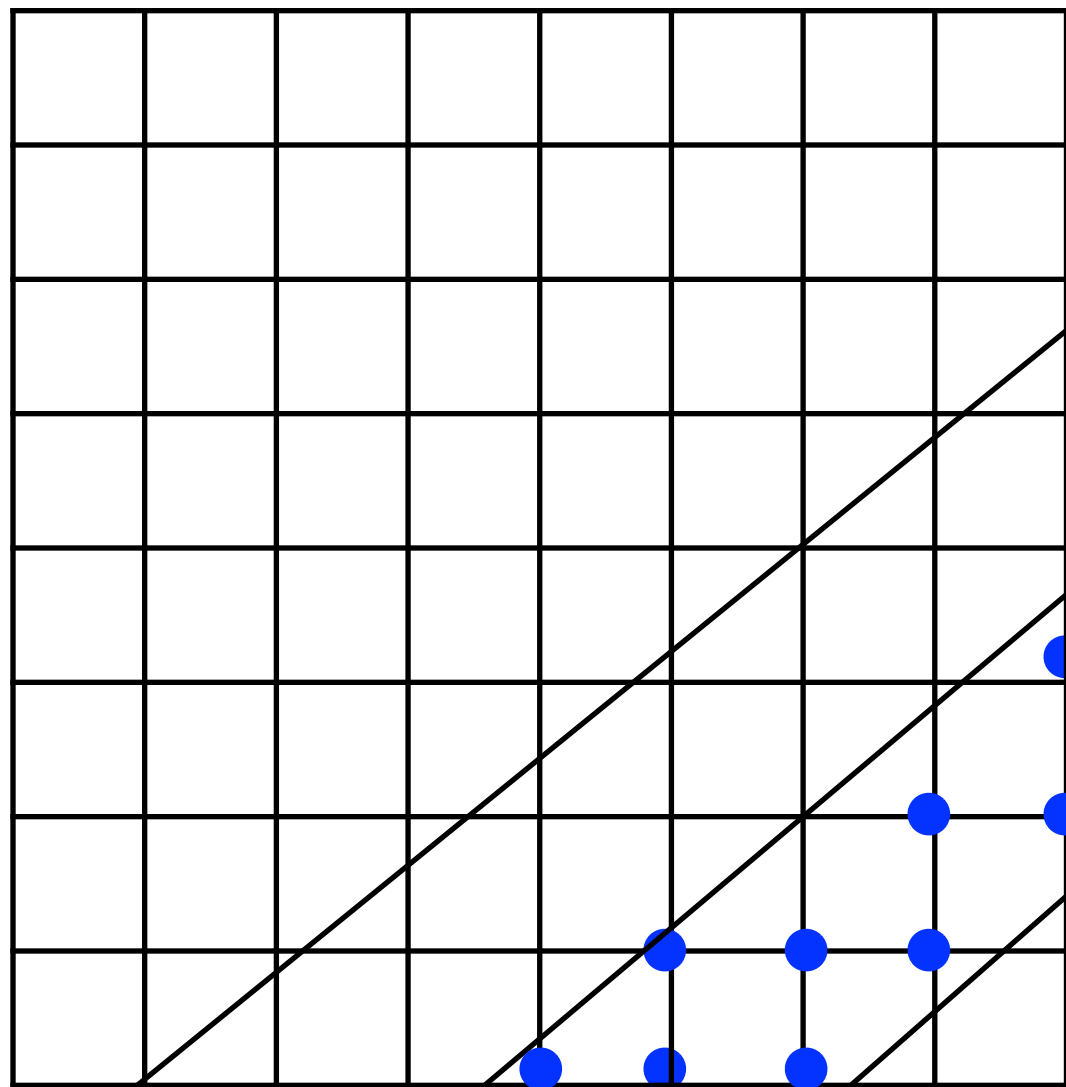




$$\mu \quad y_\mu = \sum_{i \in \partial \mu} s_i$$

Prior knowledge on  $\{s_i\}$ :  
neighboring pixels more  
likely to be equal





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Prior knowledge on  $\{s_i\}$ :  
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$$P(S) = \prod_{ij \in \text{grid}} e^{J s_i s_j} \prod_{\mu} \delta \left( y_\mu, \sum_{i \in \partial \mu} s_i \right)$$

prior

measurement

Studied with  
mean-field



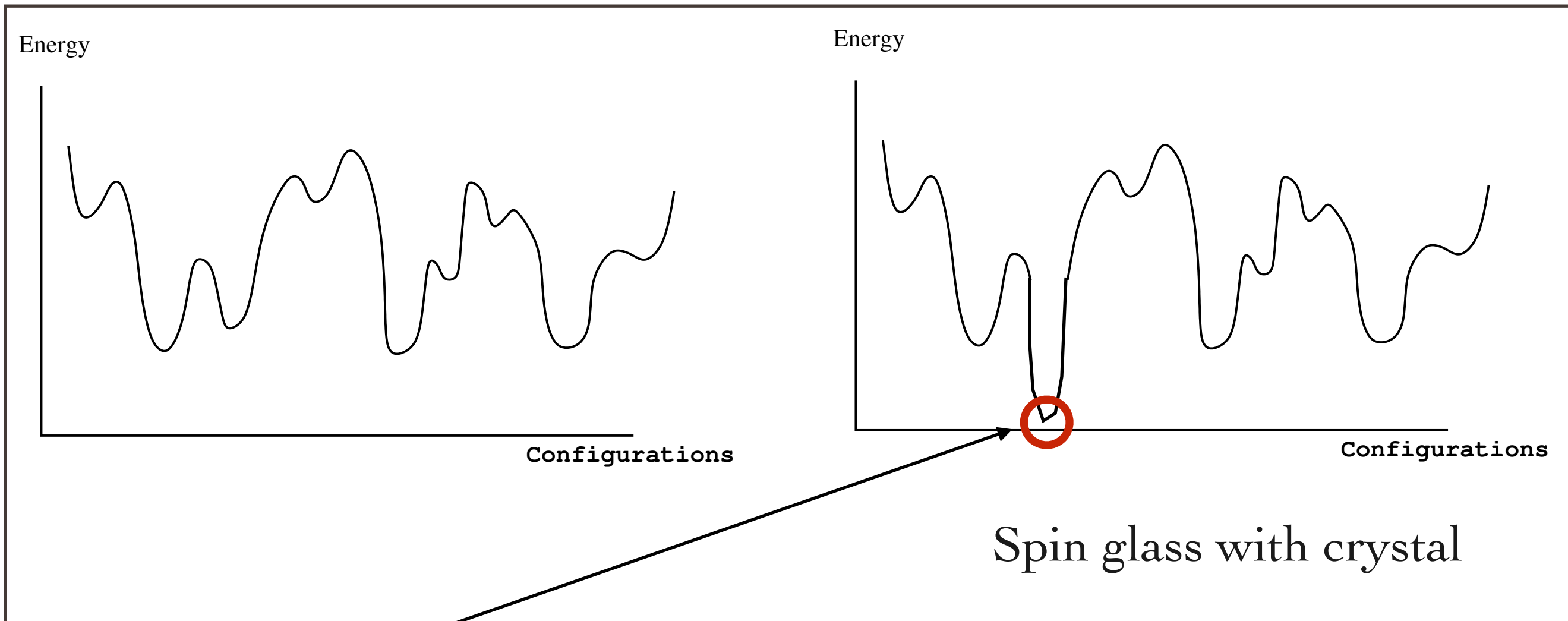
$$P(S) = \prod_{ij \in \text{grid}} e^{J s_i s_j} \prod_{\mu} \delta \left( y_{\mu}, \sum_{i \in \partial \mu} s_i \right)$$

If enough measurements: The most probable  $S$  (the ground state) gives the perfect composition of the sample.

« **Crystal** » : much more probable







« **Crystal** » : much more probable

But in some cases « crystal hunting »  
may be computationally very hard !





Inference with many unknowns :  
« crystal hunting » with mean-field  
based algorithms



# Historical development of mean field equations :

## - In homogeneous ferromagnets:

- Weiss (infinite range, 1907)
- Bethe Peierls (finite connectivity, 1935)

## - In glassy systems:

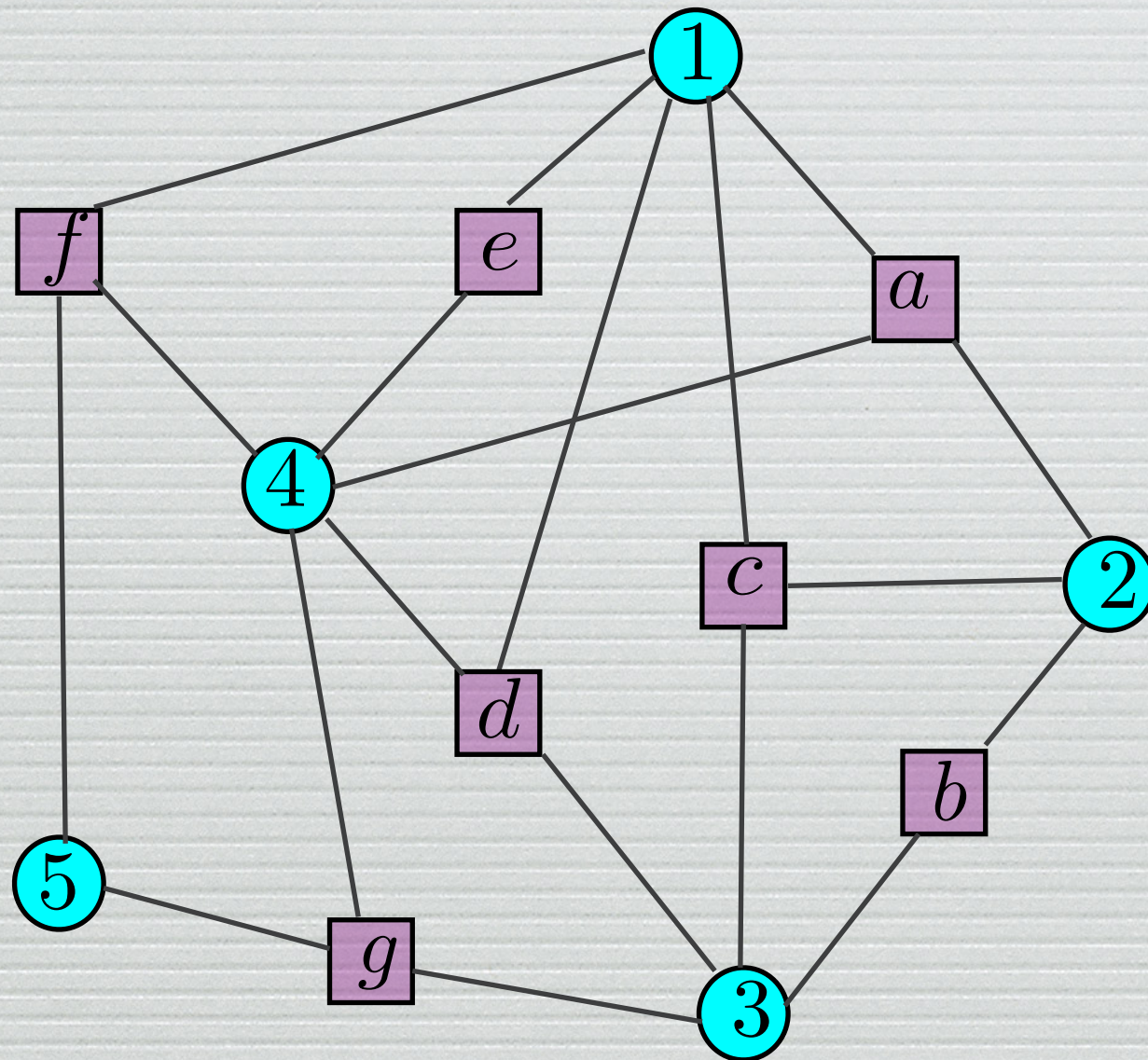
- Thouless Anderson Palmer 1977,
- MM Parisi Virasoro 1986 (infinite range)
- MM Parisi 2001 (finite connectivity)

## - As an algorithm:

- Gallager 1963
- Pearl 1986
- MM Parisi Zecchina 2002
- Kabashima 2003, 2008
- Donoho Bayati Montanari 2009
- Rangan 2010
- Krzakala MM Zdeborova 2012



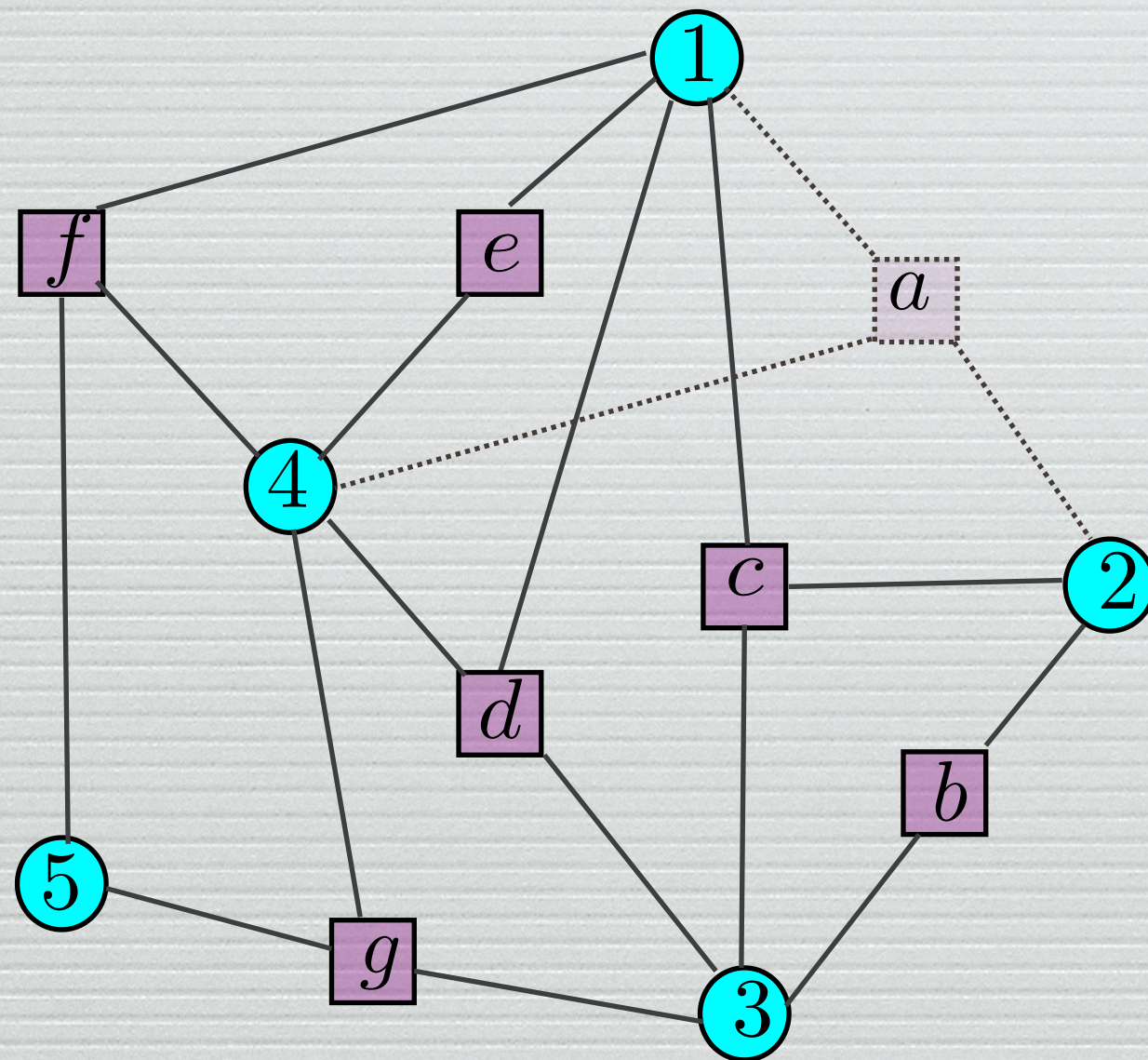
BP = Bethe-Peierls = Belief Propagation



$$P(x_1, \dots, x_5) = \psi_a(x_1, x_2, x_4) \psi_b(x_2, x_3) \cdots$$



# BP equations



First type of messages:

Probability of  $x_1$  in the absence of a:

$$m_{1 \rightarrow a}(x_1)$$

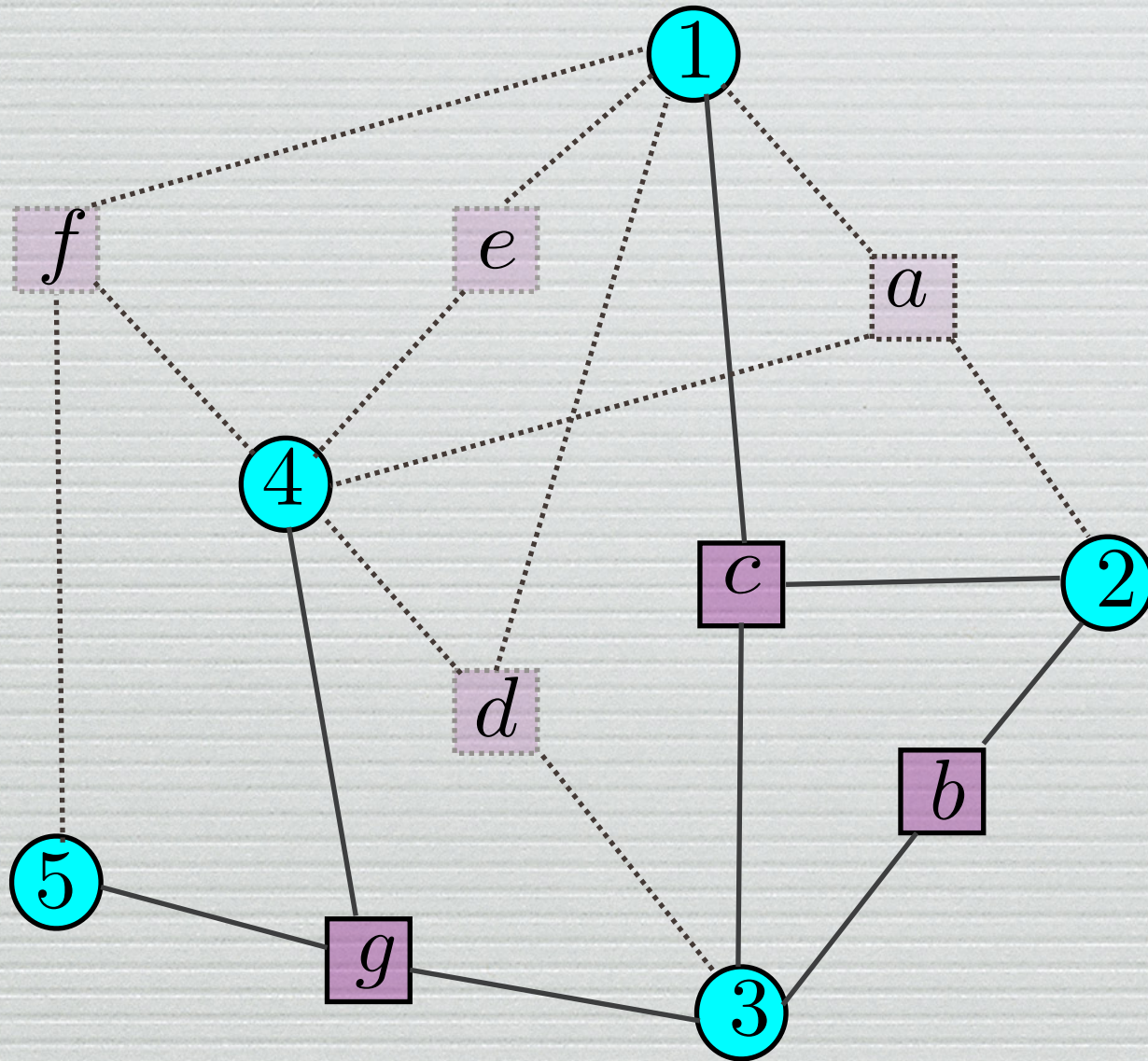


# BP equations

Second type of messages:

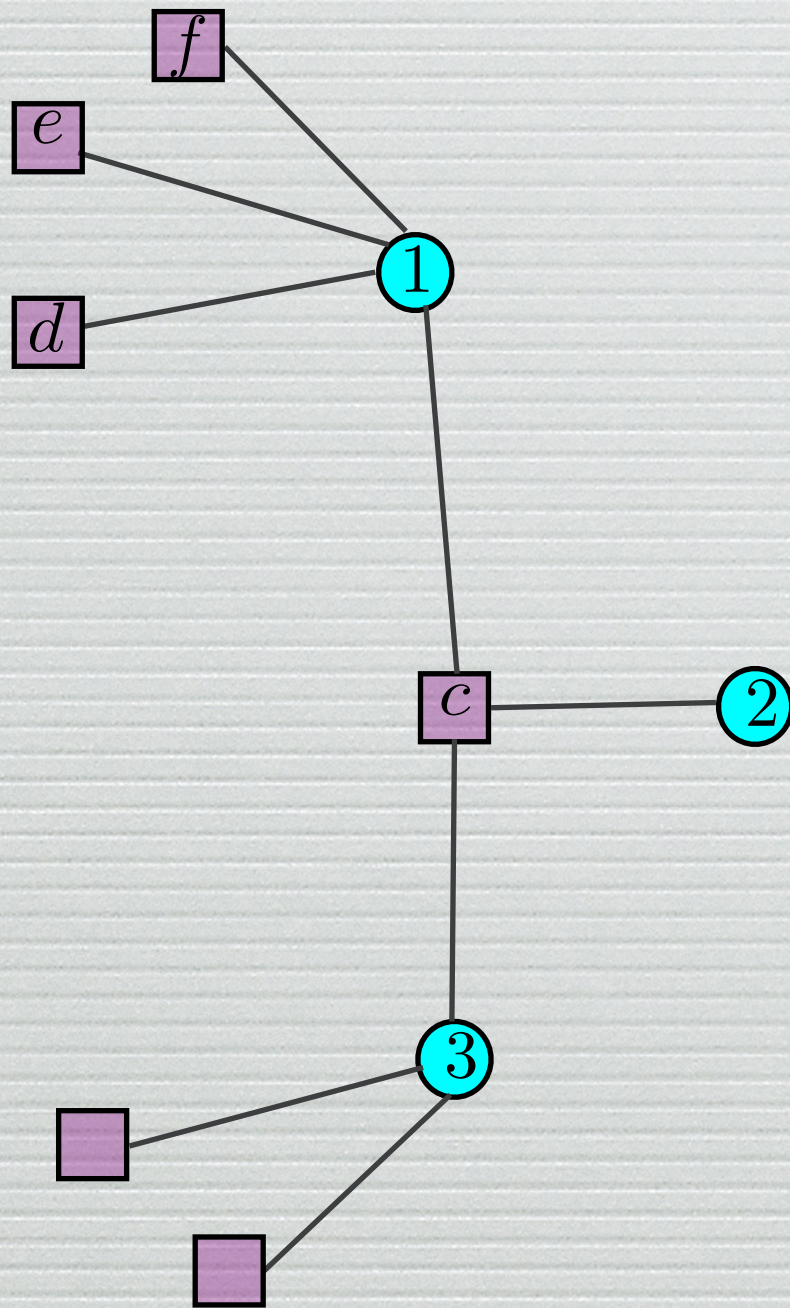
Probability of  $x_1$  when it is connected only to  $c$  :

$$m_{c \rightarrow 1}(x_1)$$



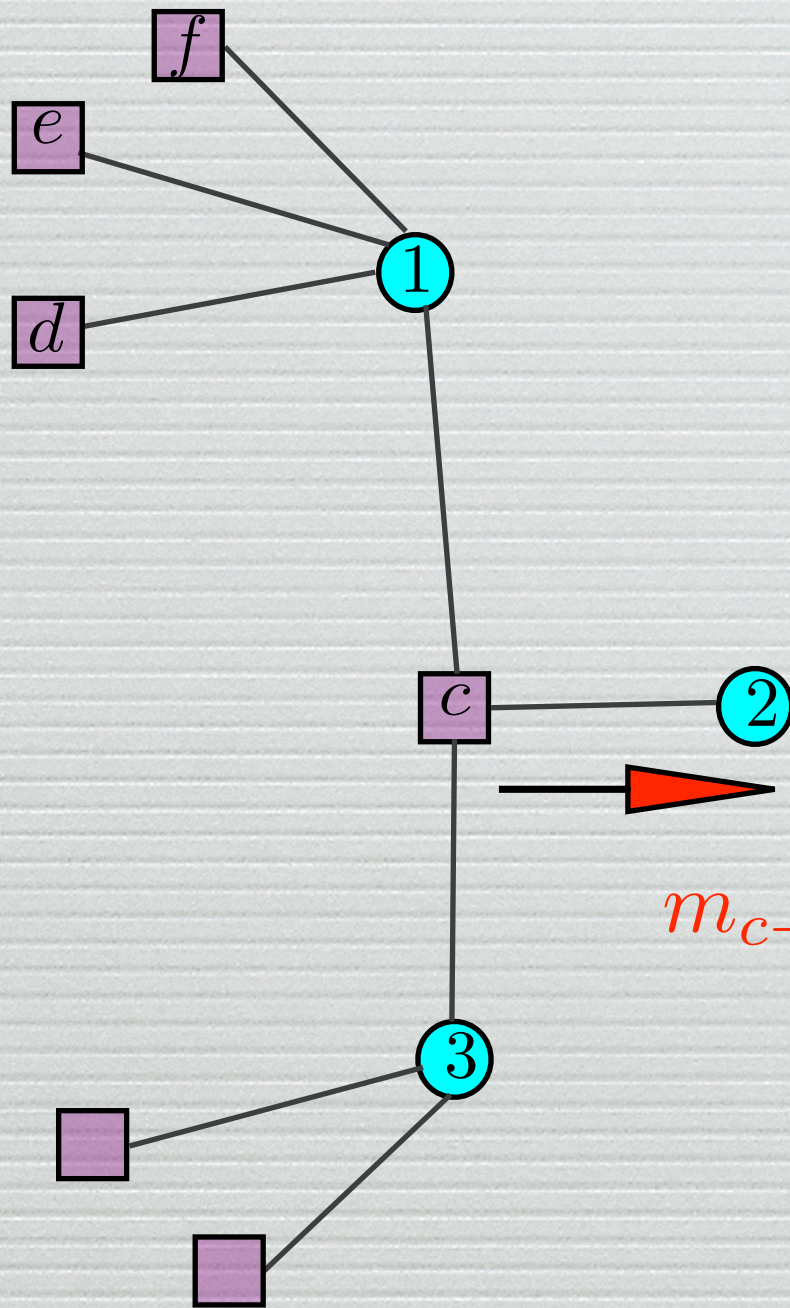


# BP equations





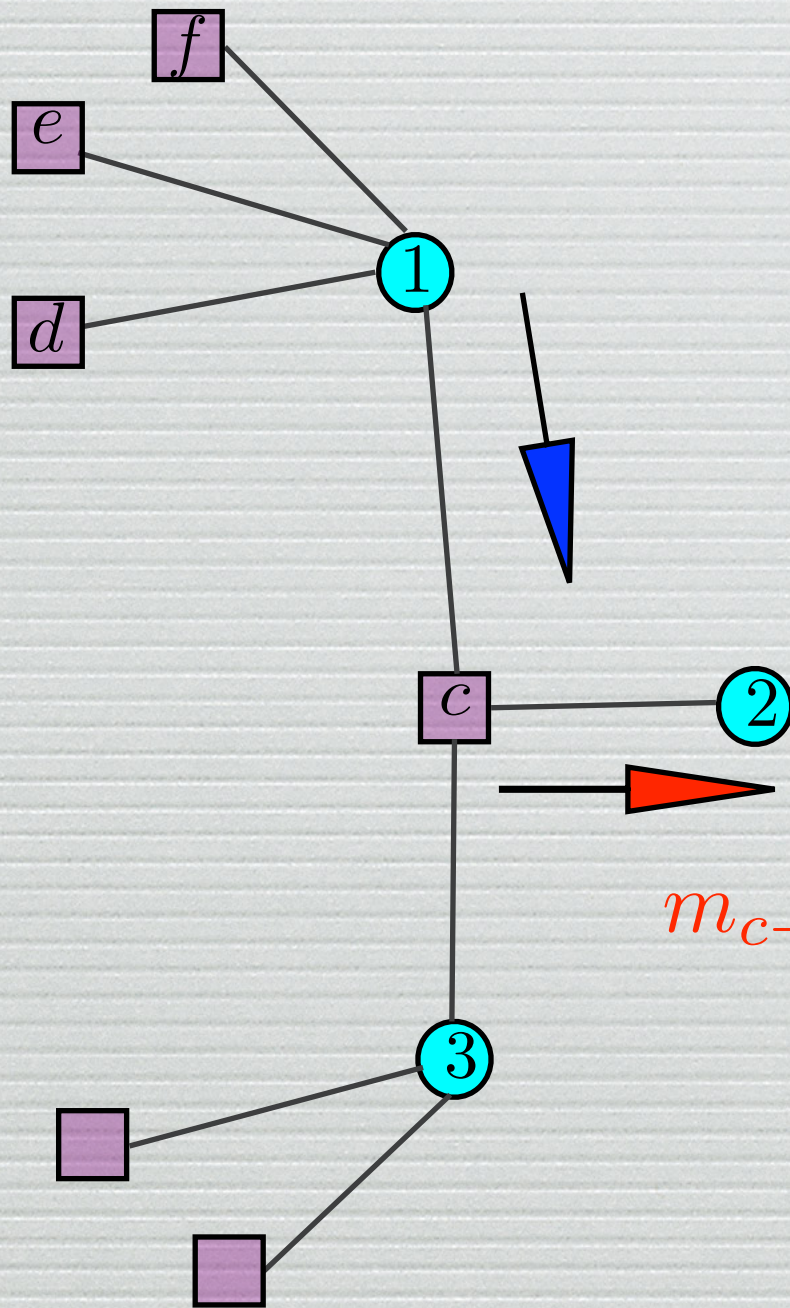
# BP equations



$$m_{c \rightarrow 2}(x_2) = \sum_{x_1, x_3} \psi_c(x_1, x_2, x_3) m_{1 \rightarrow c}(x_1) m_{3 \rightarrow c}(x_3)$$



# BP equations

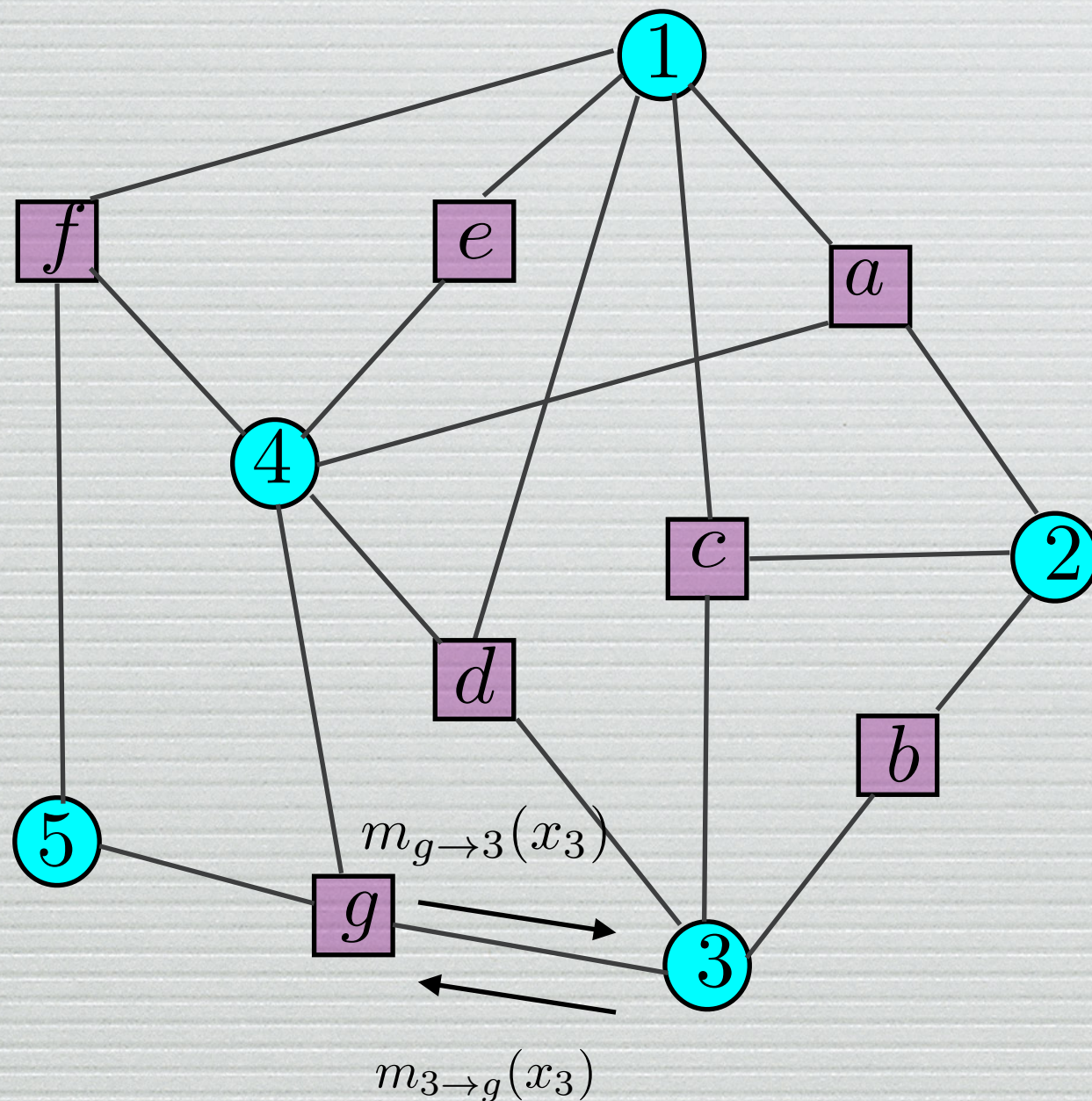


$$m_{1 \rightarrow c}(x_1) = C m_{d \rightarrow 1}(x_1) m_{e \rightarrow 1}(x_1) m_{f \rightarrow 1}(x_1)$$

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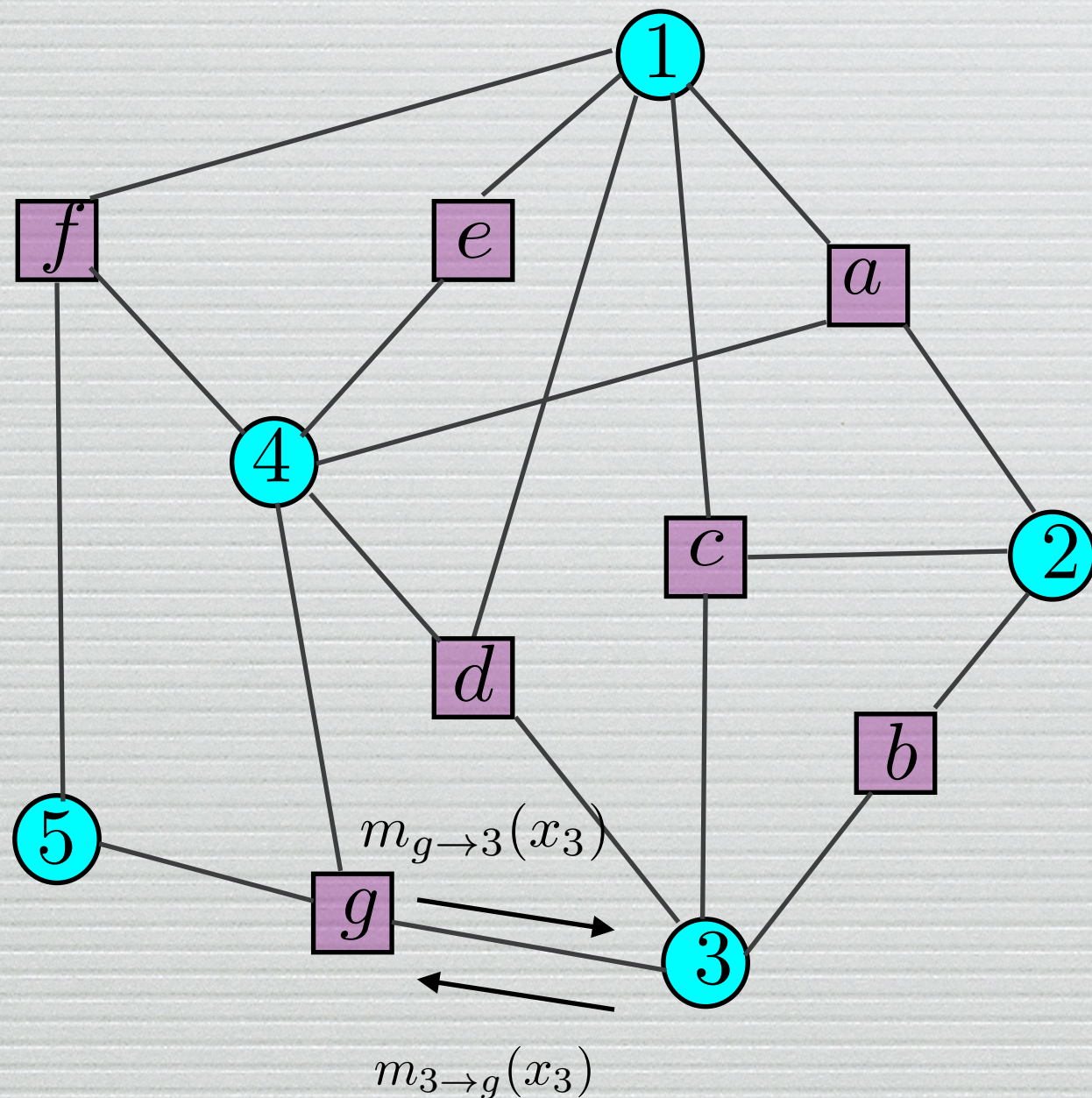
# BP equations



Propagate messages along the edges, update messages at vertices, using elementary local probabilistic rules



# BP equations



Propagate messages along the edges, update messages at vertices, using elementary local probabilistic rules

Closed set of equations: two messages “propagate” on each edge of the factor graph.



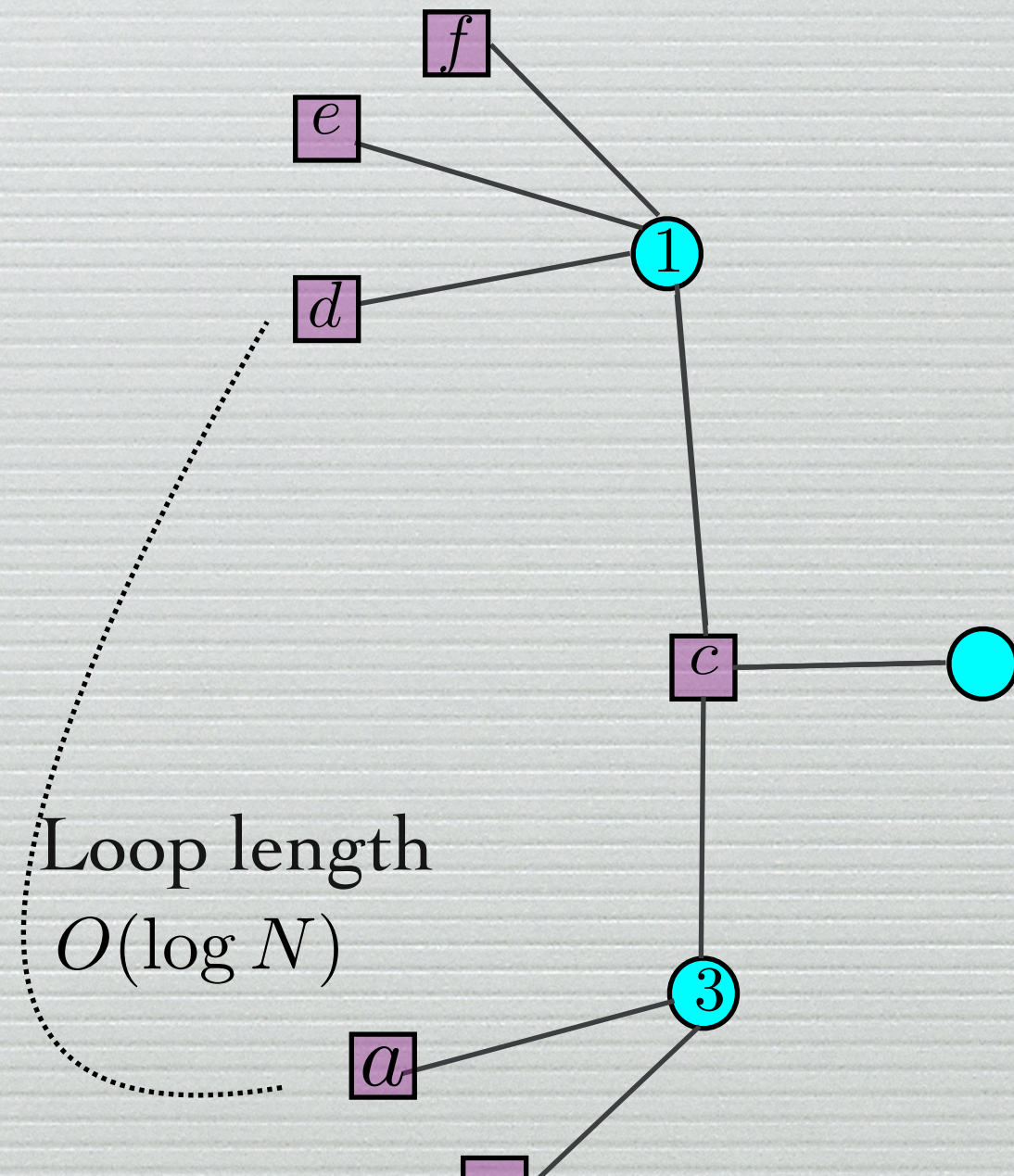
## When is BP exact?

$$m_{1 \rightarrow c}(x_1) = C m_{d \rightarrow 1}(x_1) m_{e \rightarrow 1}(x_1) m_{f \rightarrow 1}(x_1)$$

$$m_{c \rightarrow 2}(x_2) = \sum_{x_1, x_3} \psi_c(x_1, x_2, x_3) m_{1 \rightarrow c}(x_1) m_{3 \rightarrow c}(x_3)$$

Fluctuations are handled correctly, but beware of correlations

- Exact in one dimension (transfer matrix = dynamic programming)
- Exact on a tree (uncorrelated b.c)
- Exact on locally tree-like graphs (Erdős Renyi etc.) if correlations decay fast enough (single pure state) and uncorrelated disorder
- Exact in infinite range problems if correlations decay fast enough (single pure state) and uncorrelated disorder



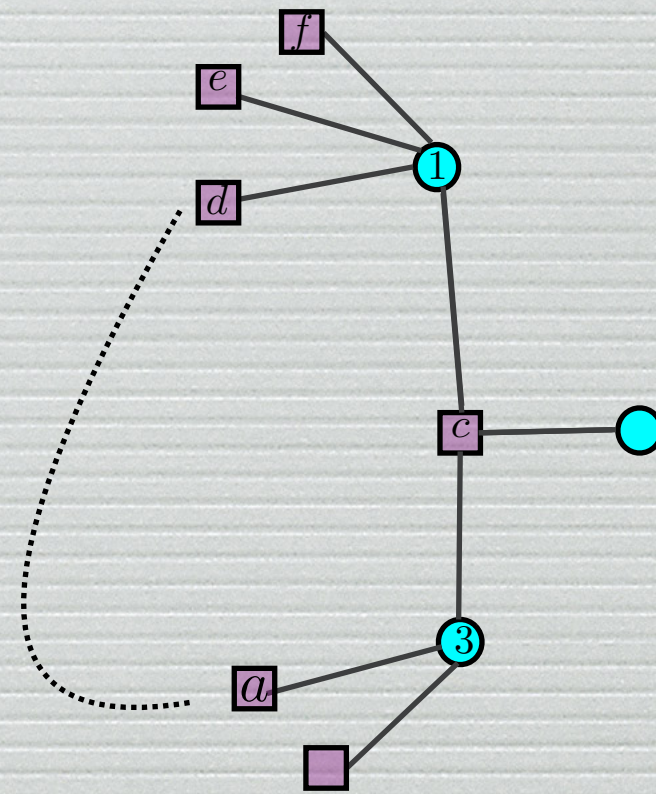


**NB:** What happens in a glass phase, when there are many pure states, and therefore many solutions ?

BP equations

$$m_{i \rightarrow \mu}(x_i) = \prod_{\nu (\neq \mu)} m_{\nu \rightarrow i}(x_i)$$

Correct if, in absence of the i-j interaction, the correlations between  $k$  and  $\ell$  can be neglected.



Loop length  $O(\log N)$

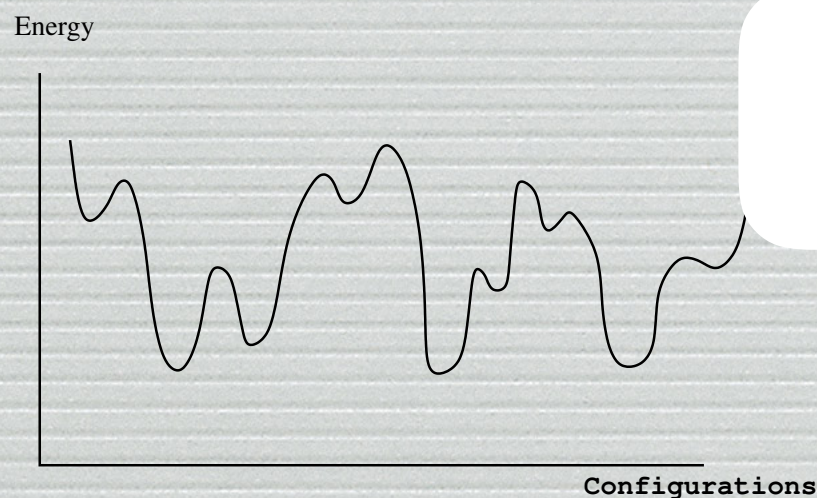


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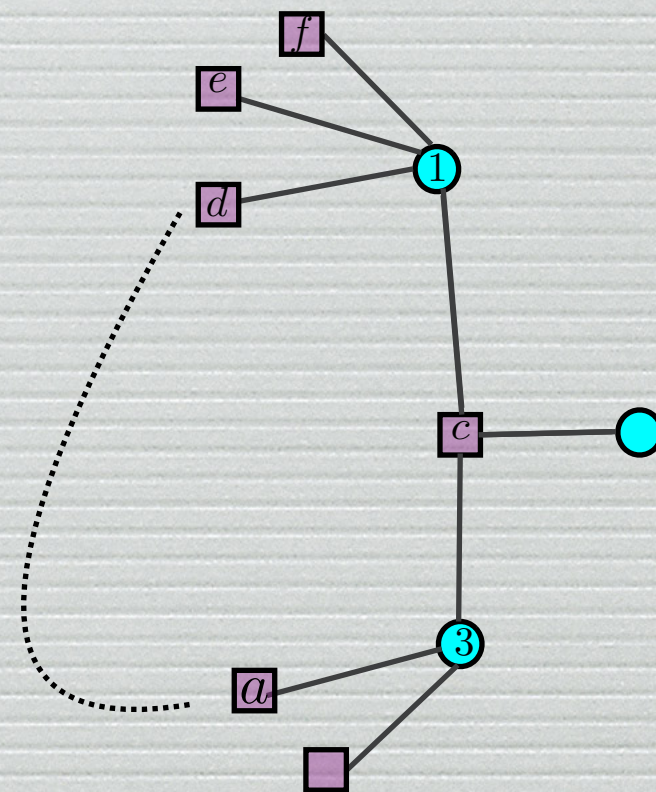
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$${}^{\alpha} m_{i \rightarrow \mu}(x_i) = \prod_{\nu (\neq \mu)} {}^{\alpha} m_{\nu \rightarrow i}(x_i)$$



**Glassy phase: many states,  
many solutions of BP**

Loop length  $O(\log N)$



## 2) What happens in a glass phase, when there are many pure states, and therefore many solutions ?

BP equations

$$m_{i \rightarrow \mu}(x_i) = \prod_{\nu (\neq \mu)} m_{\nu \rightarrow i}(x_i)$$

Statistics of  $m_{i \rightarrow \mu}^{\alpha}(x_i)$   
over the many states  $\alpha$

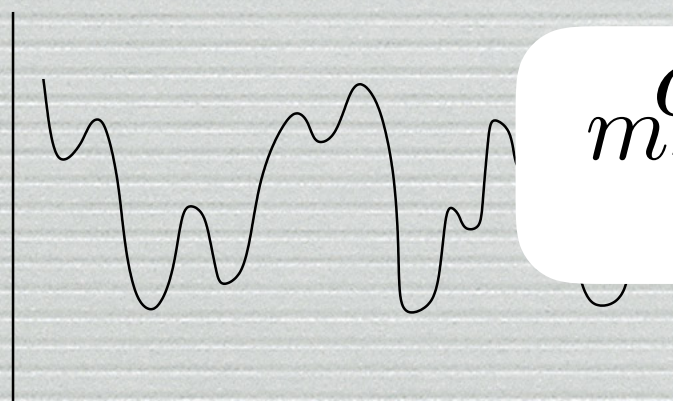
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$$P_{i \rightarrow \mu}(m)$$

related to

$$P_{\nu \rightarrow i}(m)$$

Energy



$$m_{i \rightarrow \mu}^{\alpha}(x_i) = \prod_{\nu (\neq \mu)} m_{\nu \rightarrow i}^{\alpha}(x_i)$$

**Survey propagation  
(SP)**  
MM Parisi Zecchina  
2002

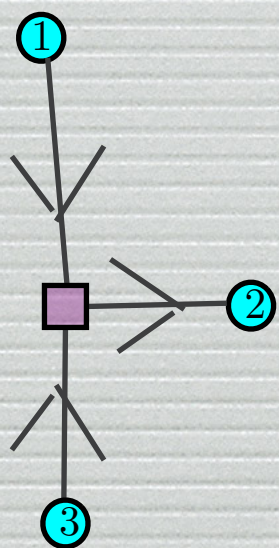
**Glassy phase: many states,  
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# Power of message passing algorithms

Approximate solution of very hard, and very large constraint satisfaction problems, ...FAST! (typically linear time)

- BP: Best decoders for LDPC error correcting codes
- SP: Best solver of random satisfiability problems
- BP: Best algorithm for learning patterns in neural networks (e.g. binary perceptron)
- Data clustering, graph coloring, Steiner trees, etc...
- Fully connected networks : TAP (=AMP). Compressed sensing, linear estimation, etc.



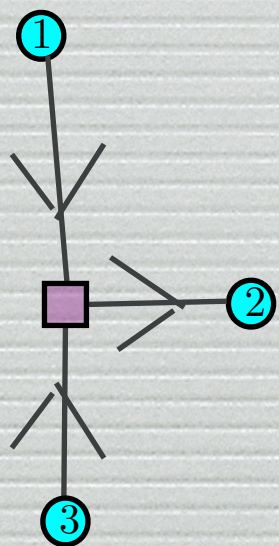
Local, simple update equations:  
Each message is updated using  
information from incoming  
messages on the same node.  
Distributed, solves hard global pb



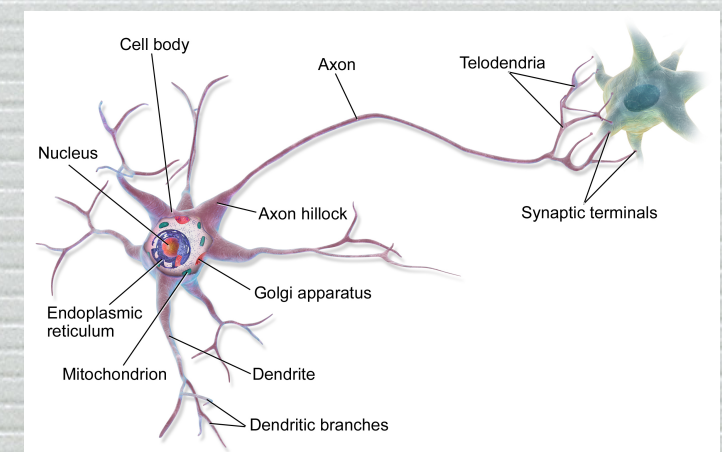
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# An example of mean-field based inference:

## Compressed sensing

Applications:

- Tomography
- MNR
- Single pixel camera
- Satellite images
- ...

Connected to:

- linear regression
- perceptron learning



# An example of mean-field based inference: Compressed sensing

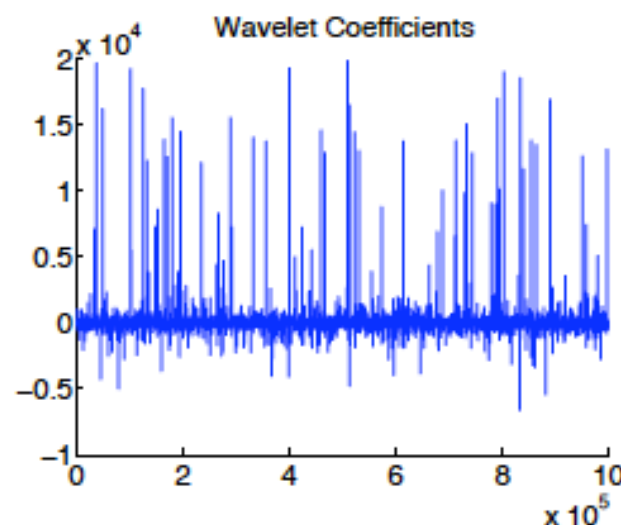
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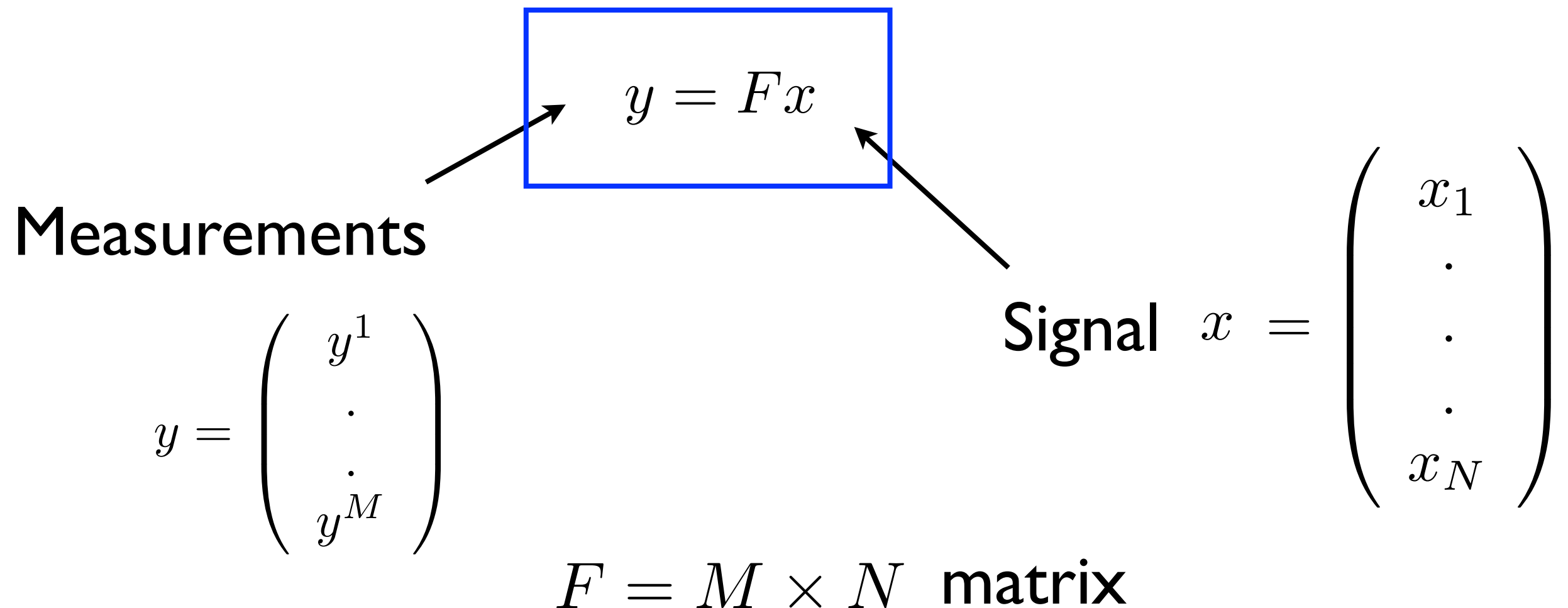
Sparse data (in appropriate basis)+  
linear measurements





# Benchmark: noiseless limit of compressed sensing with iid measurements

System of linear measurements



Random  $F$  : «random projections» (incoherent with signal)

Pb: Find  $x$  when  $M < N$  and  $x$  is sparse



# Phase diagram

«Thermodynamic limit»

$N \gg 1$  variables

$R = \rho N$  non-zero variables

$M = \alpha N$  equations

● Solvable by enumeration when  $\alpha > \rho$  but  $O(e^N)$

●  $\ell_1$  norm approach

Find a  $N$  - component vector  $x$  such that the  $M$  equations  $y = Fx$  are satisfied and  $\|x\|_1$  is minimal

● AMP = Bayesian approach

Planted:  $\phi_T(x)$

$$P(\mathbf{x}) = \prod_{i=1}^N [(1 - \rho)\delta(x_i) + \rho\phi(x_i)] \prod_{\mu=1}^P \delta\left(y_\mu - \sum_i F_{\mu i} x_i\right)$$

↑



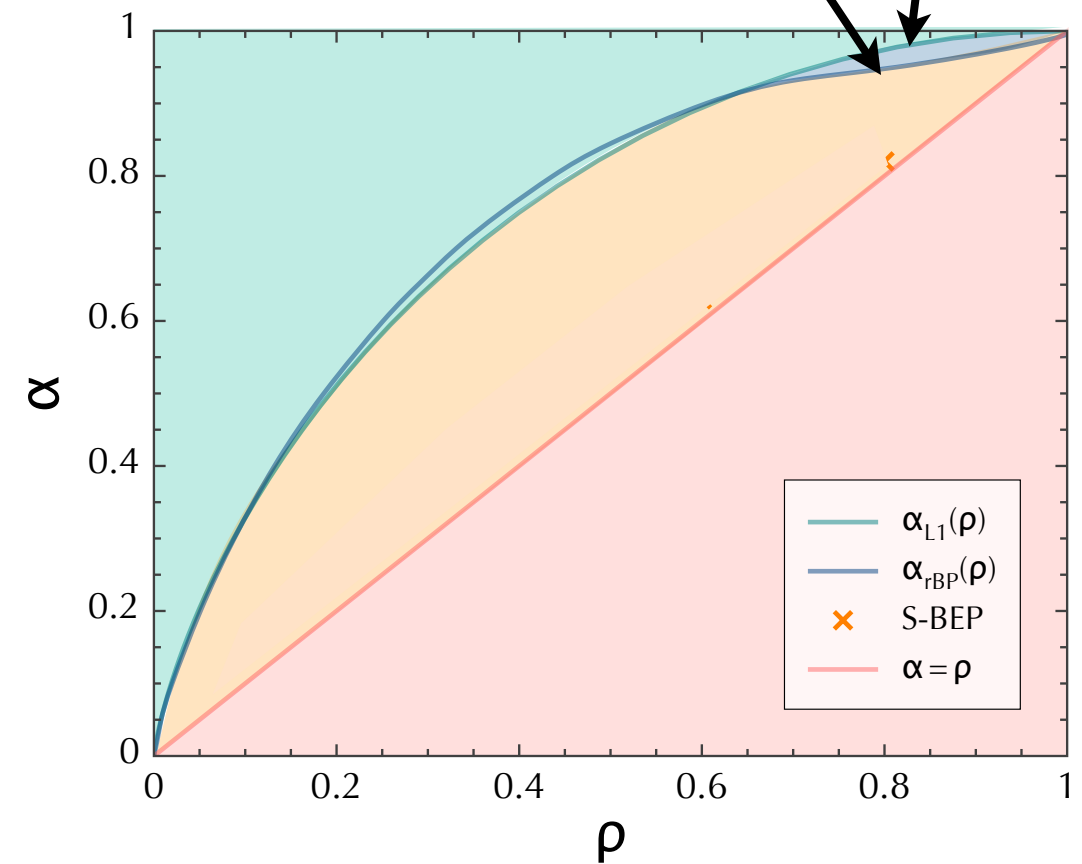
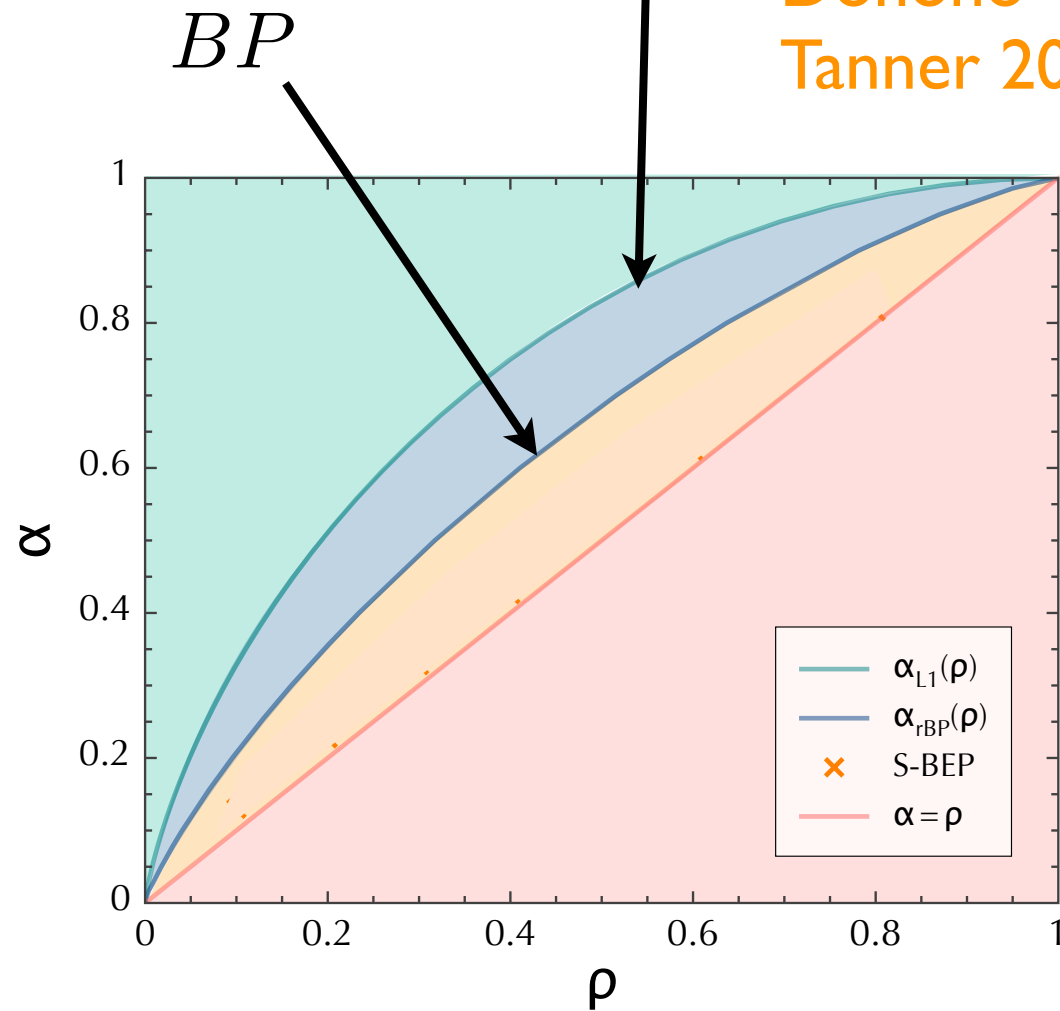
# Performance of AMP with Gauss-Bernoulli prior: phase diagram

Krzakala Sausset  
Mézard Sun  
Zdeborova 2011

Donoho  
2006,  
Donoho  
Tanner 2005

$BP$

$L_1$



Gaussian signal

Binary signal

$$\phi_T(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$$

$$\phi_T(x) = \frac{1}{2} (\delta_{x,1} + \delta_{x,-1})$$

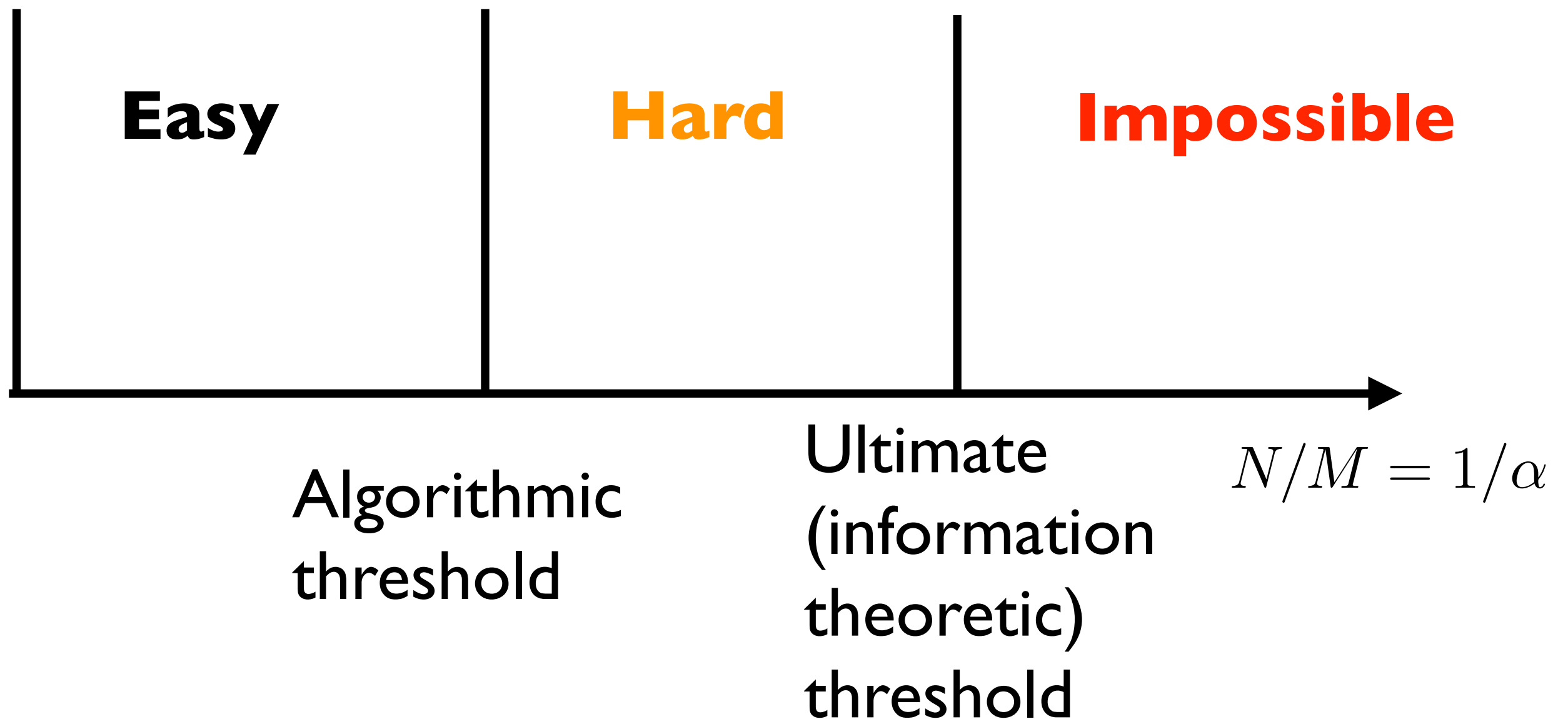


# Analysis of random instances : phase transitions

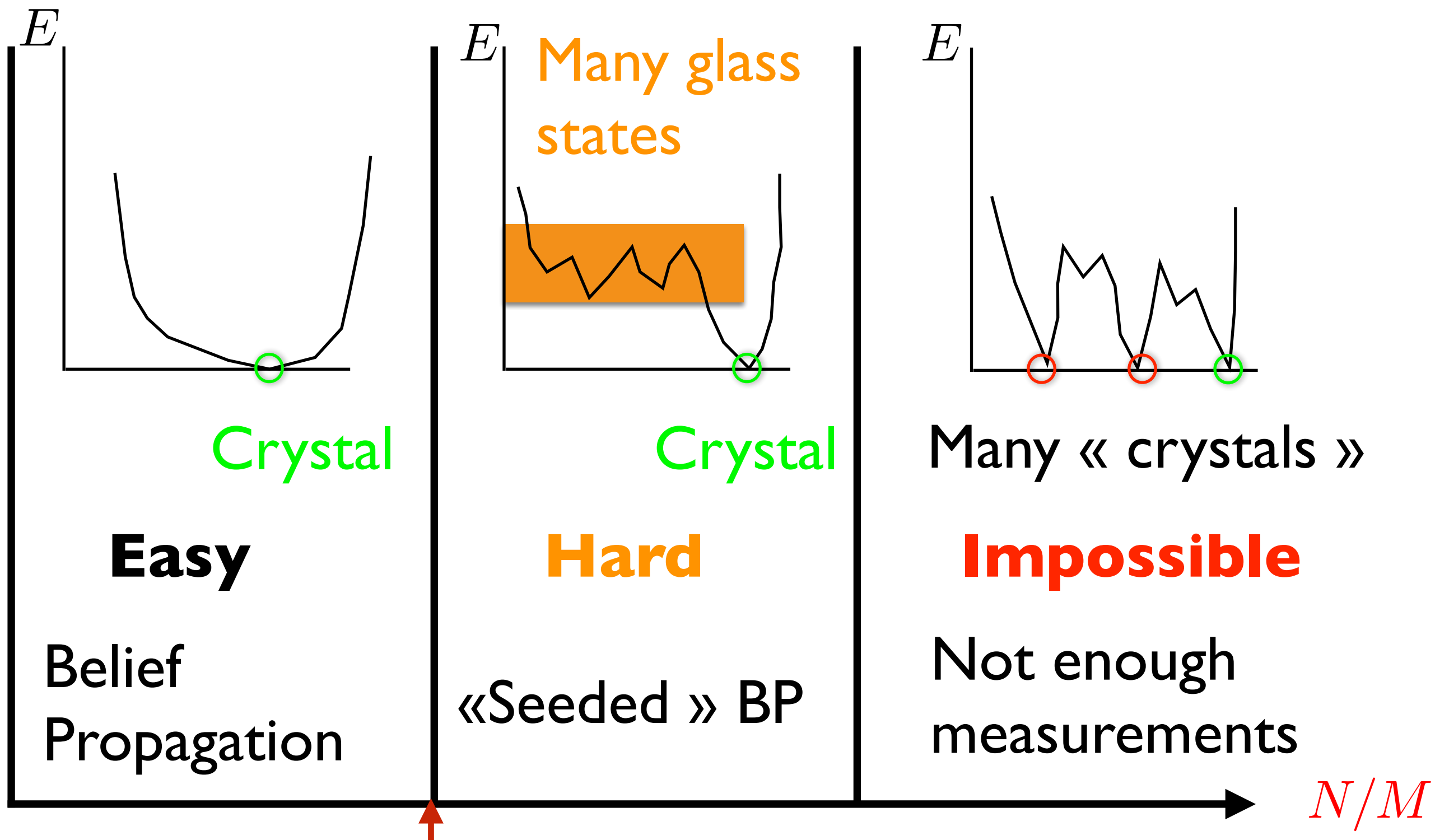
$N$  (real) variables,  $M$  measurements (linear functions)

Analysis of random instances : phase transitions

Reconstruction of signal using BP. Fixed  $\rho$ , decrease  $\alpha$







Dynamical phase transition. Ubiquitous in statistical inference. Conjecture « All local algorithms freeze »... How universal?



## Step 3: design the measurement matrix in order to get around the glass transition

Getting around the glass trap: design the matrix  $F$  so that one nucleates the naive state (crystal nucleation idea,  
...borrowed from error correcting codes : « spatial coupling »)

Felström-Zigangirov,  
Kudekar Richardson Urbanke,  
Hassani Macris Urbanke,  
...

«Seeded BP»



# Nucleation and seeding





# Nucleation and seeding





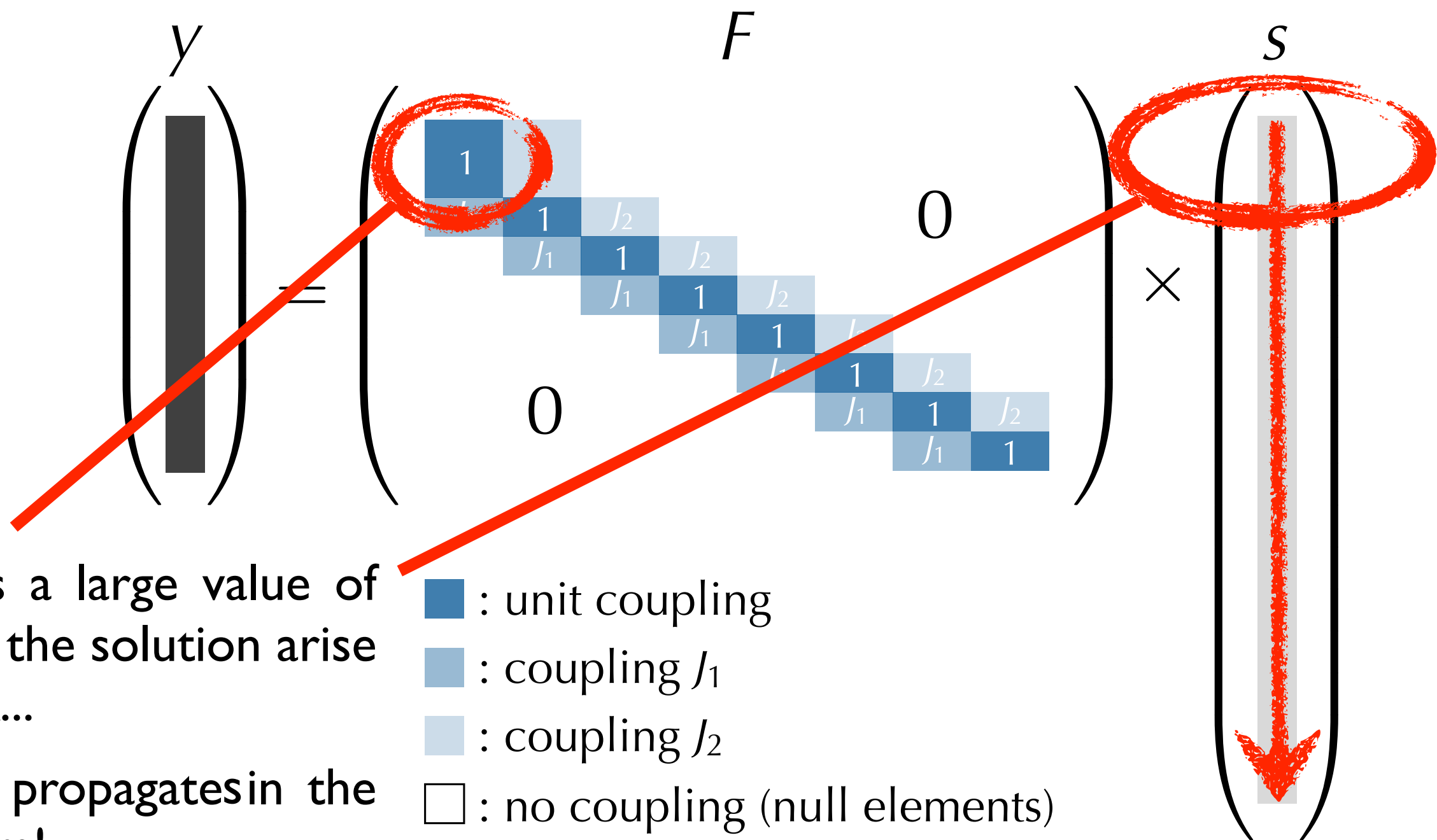
$$\begin{pmatrix} y \\ \vdots \end{pmatrix} = \begin{pmatrix} \begin{matrix} 1 & j_2 & & & & \\ j_1 & 1 & j_2 & & & \\ & j_1 & 1 & j_2 & & \\ & & j_1 & 1 & j_2 & \\ & & & j_1 & 1 & j_2 \\ & 0 & & & & 0 \\ & & 0 & & & & 0 \end{matrix} \\ 0 \end{pmatrix} \times \begin{pmatrix} s \\ \vdots \end{pmatrix}$$

■ : unit coupling  
 ■ : coupling  $j_1$   
 ■ : coupling  $j_2$   
 □ : no coupling (null elements)

Structured  
measurement matrix.  
Variances of the  
matrix elements

$F_{\mu i}$  = independent random Gaussian variables,  
zero mean and variance  $J_{b(\mu)b(i)}/N$





Block 1 has a large value of  $M$  such that the solution arise in this block...

... and then propagates in the whole system!

- : unit coupling
- : coupling  $J_1$
- : coupling  $J_2$
- : no coupling (null elements)

$$L = 8$$

$$N_i = N/L$$

$$M_i = \alpha_i N/L$$

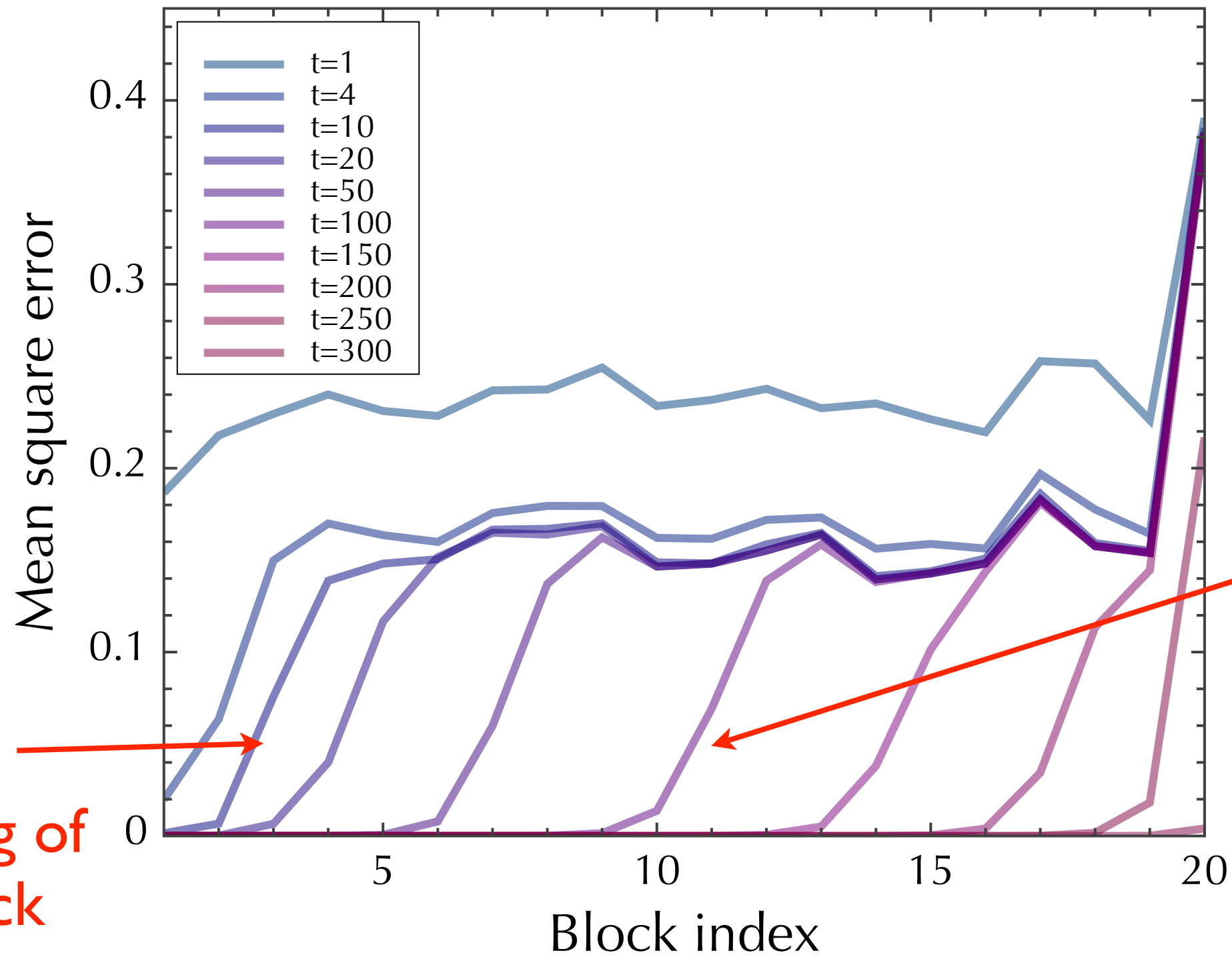
$$\alpha_1 > \alpha_{BP}$$

$$\alpha_j = \alpha' < \alpha_{BP} \quad j \geq 2$$

$$\alpha = \frac{1}{L} (\alpha_1 + (L - 1)\alpha')$$



# Numerical study



$t = 100$   
decoding  
of blocks  
1 to 9

$t = 10$   
decoding of  
first block

$$L = 20$$

$$N = 50000$$

$$\rho = .4$$

$$J_1 = 20$$

$$\alpha_1 = 1$$

$$J_2 = .2$$

$$\alpha = .5$$



# Performance of the probabilistic approach + message passing + parameter learning+ seeding matrix

$$Z = \int \prod_{j=1}^N dx_j \prod_{i=1}^N [(1 - \rho)\delta(x_i) + \rho\phi(x_i)] \prod_{\mu=1}^M \delta\left(y_\mu - \sum_{i=1}^N F_{\mu i} x_i\right)$$

$$F = \begin{pmatrix} \begin{array}{cccccccc} 1 & J_2 & & & & & & \\ J_1 & 1 & J_2 & & & & & \\ & J_1 & 1 & J_2 & & & & \\ & & J_1 & 1 & J_2 & & & \\ & & & J_1 & 1 & J_2 & & \\ & & & & J_1 & 1 & J_2 & \\ & & & & & J_1 & 1 & J_2 \\ 0 & & & & & & J_1 & 1 \end{array} \\ 0 \end{pmatrix}$$

- Simulations
- Analytic approaches (replicas and cavity)

$$\rightarrow \alpha_c = \rho_0$$

Reaches the ultimate information-theoretic threshold

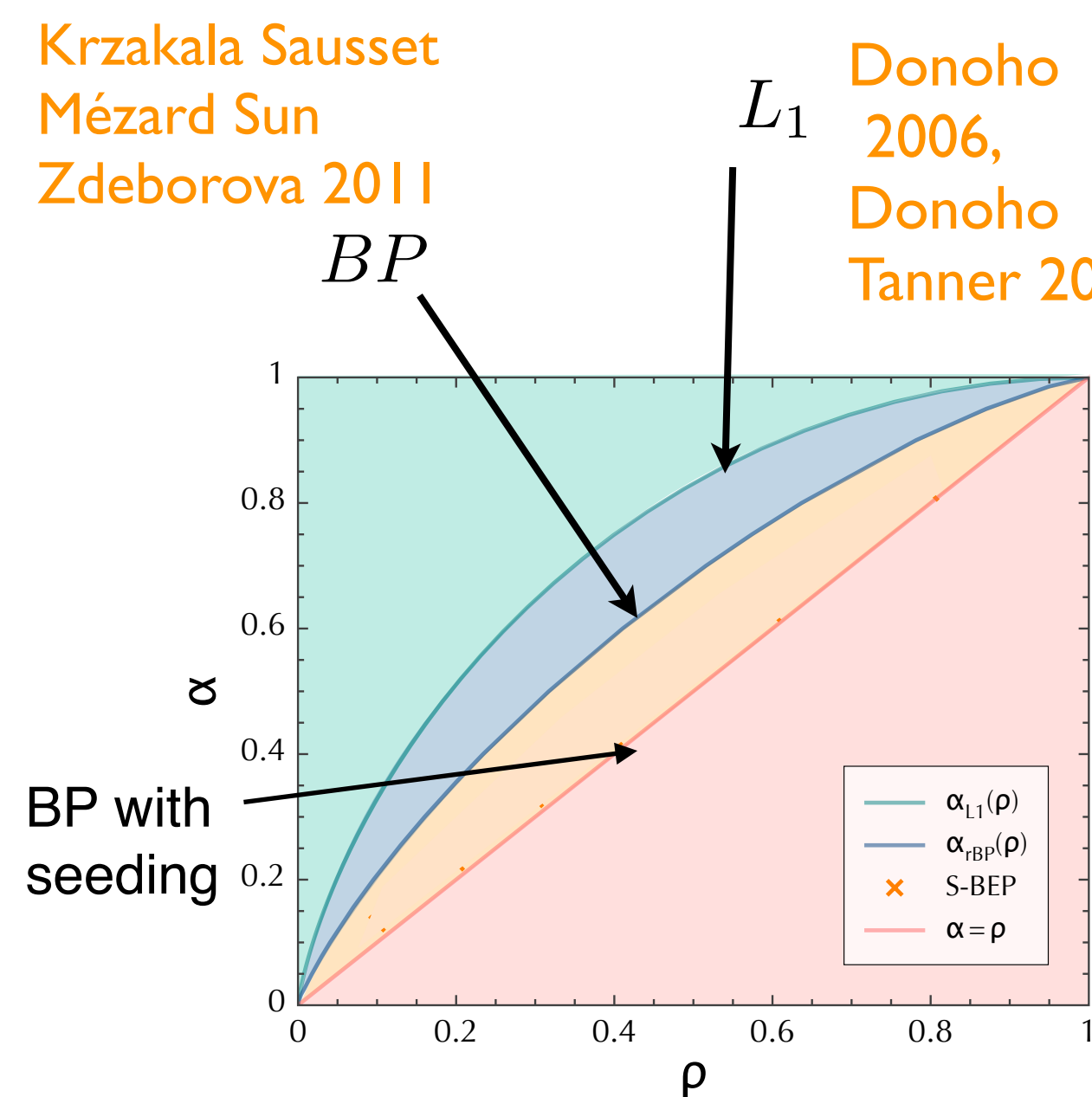
Proof: Donoho Javanmard Montanari



# Performance of AMP with Gauss-Bernoulli prior: phase diagram

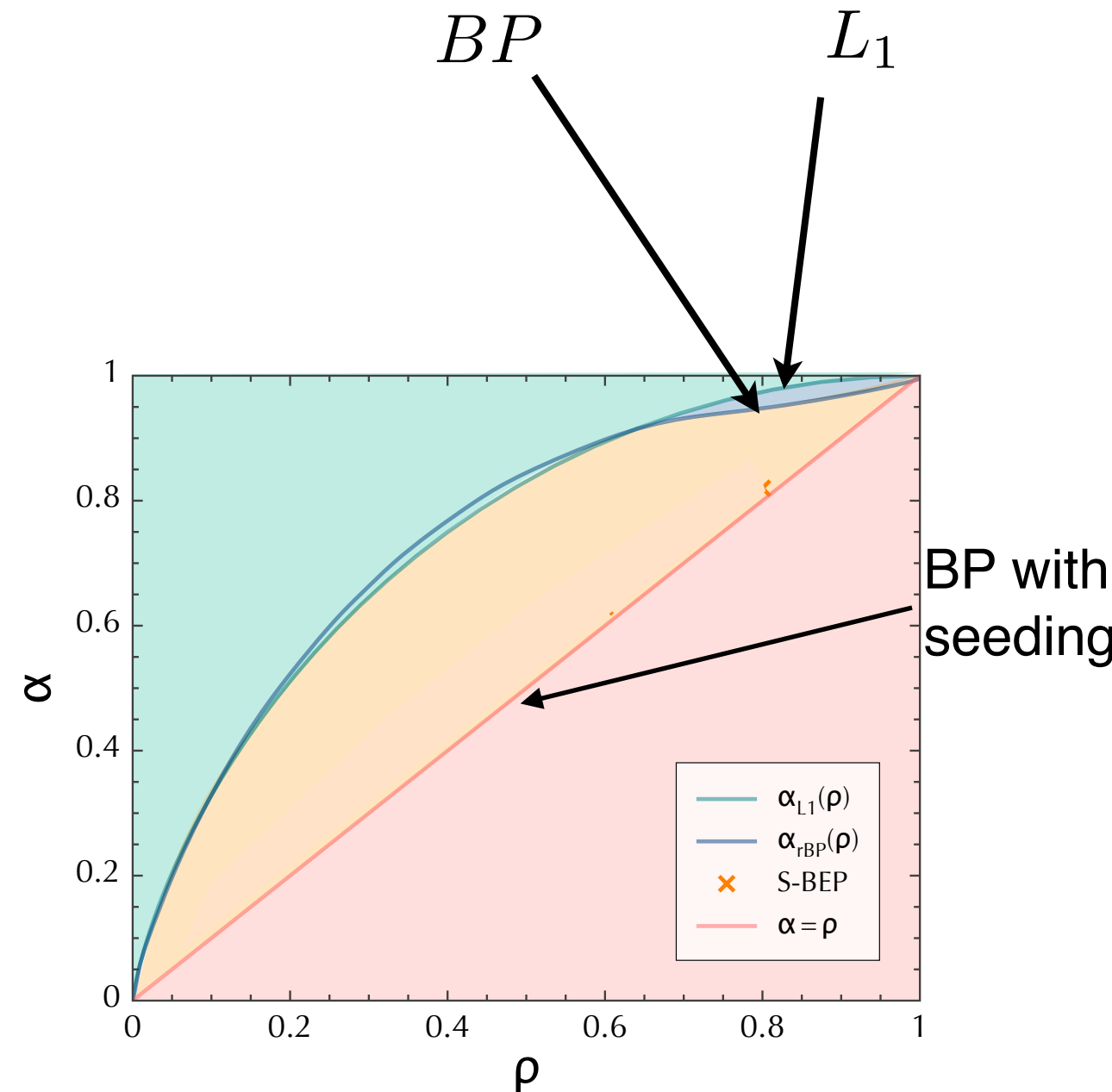
Krzakala Sausset  
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2006,  
Donoho  
Tanner 2005



Gaussian signal

$$\phi_T(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$$



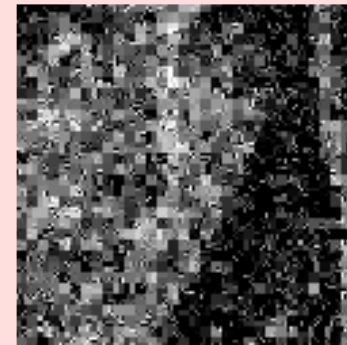
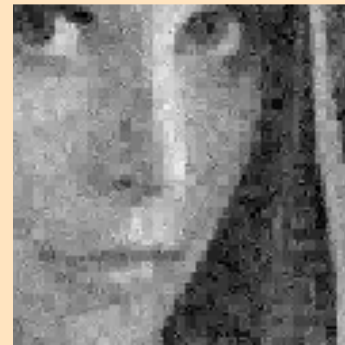
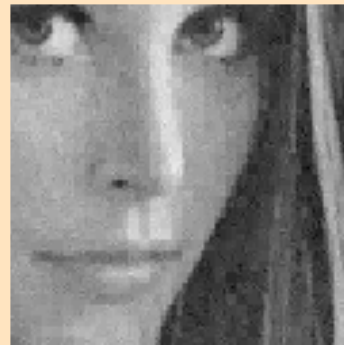
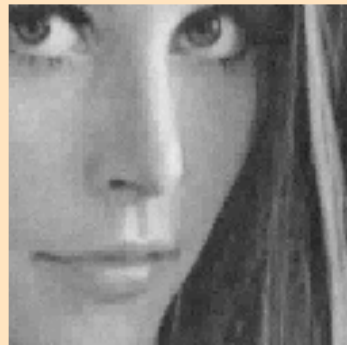
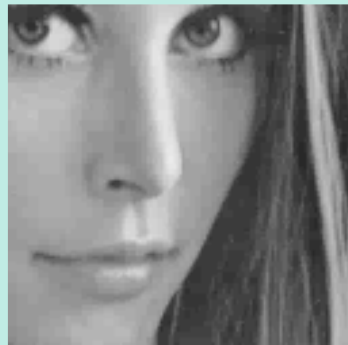
Binary signal

$$\phi_T(x) = \frac{1}{2} (\delta_{x,1} + \delta_{x,-1})$$

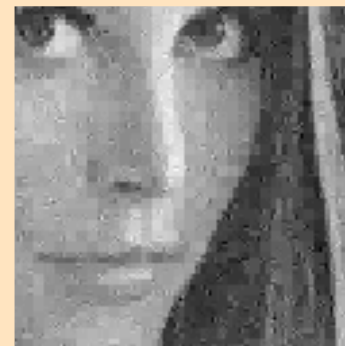
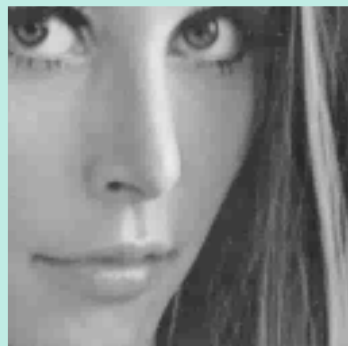


$$\alpha = \rho \approx 0.24$$

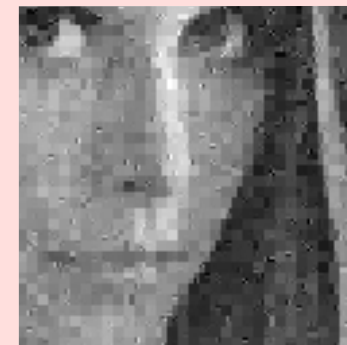
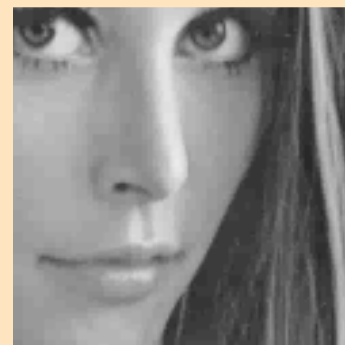
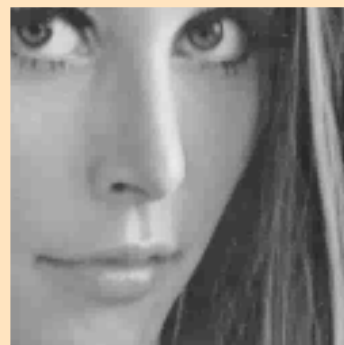
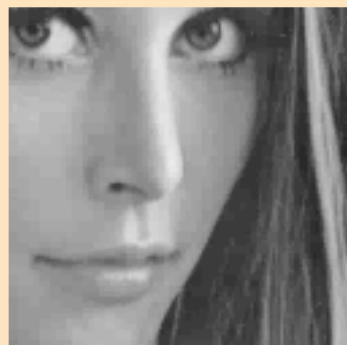
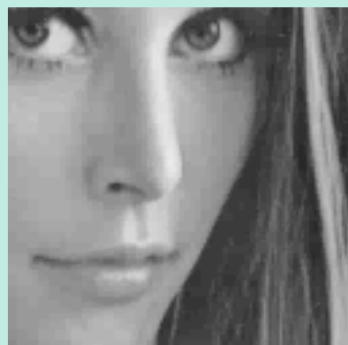
$L_1$



BEP



s-BP



$\alpha = 0.6$

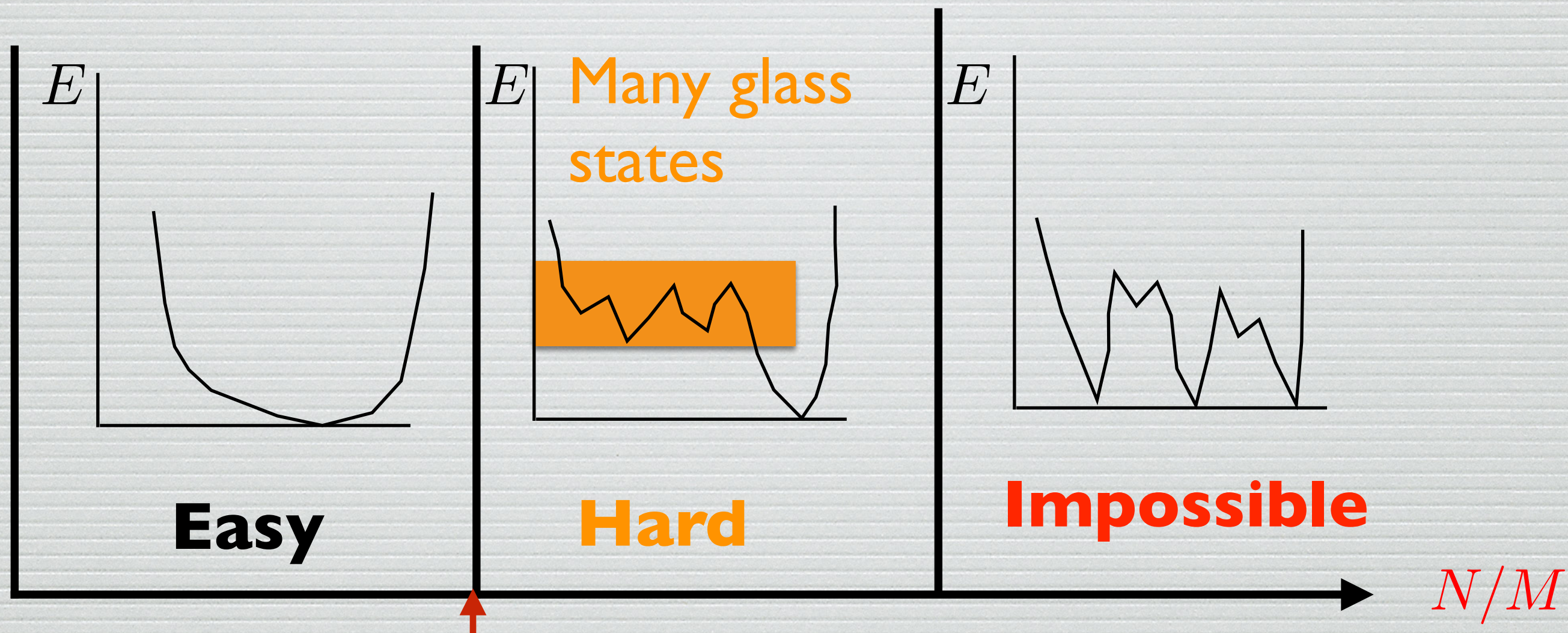
$\alpha = 0.5$

$\alpha = 0.4$

$\alpha = 0.3$

$\alpha = 0.2$





Phase transitions are crucial in large inference problems

Hard-Impossible = absolute limit (Shannon-like)

Easy- Hard = limit for large class of algorithms (local)



# The spin glass cornucopia

A very sophisticated and powerful corpus of conceptual and methodological approaches has been developed (replicas, cavity, TAP,...) mostly in the years 1975-2000, and has found applications in many different fields of information theory and computer science

*Portrait of Ottavio Strada,*

*Tintoretto, Venice 1567*

*Rijk's Museum Amsterdam*





# Thanks

Jean Barbier, Emmanuelle Gouillart, Yoshiyuki  
Kabashima, Florent Krzakala, Ayaka Sakata, François  
Sausset, Yifan Sun, Lenka Zdeborova, Pan Zhang,...







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